SOLCON™ POWERED

MPS 3000

Motor Protection System

Instruction Manual

Ver. 06 August 2009

1. Table of Contents

Note

Installation, operation and maintenance should be in strict accordance with the instructions in this manual, national codes and good practice. Installation or operation not performed in strict accordance with these instructions shall void the manufacturer's warranty.

Note

Disconnect all power inputs before wiring or servicing the equipment.

Warning

Unit must be grounded to insure correct operation and safety.

2. Introduction

The MPS 3000 Motor Protection System is a new generation of micro processor based relay / controller designed to operate with a three (3) phase induction motors.
True RMS voltages and currents are measured at a sampling rate of 0.5 ms, enables the MPS3000 to be used with electronic motor drives like soft starters.
The MPS3000 incorporates two main features.

a. Motor protection.
b. Supervision and communication.

The MPS3000-C is identical to MPS3000, but incorporates in addition to all MPS3000 features, also:

c. Motor control.

2.1. Protection Features

AC motors are very rugged and reliable when operating within product specification limits. However, they are usually designed to operate close to their rated limits with minimal margins for operating under abnormal conditions.
A comprehensive protection device is required to accurately create a Thermal Modeling, in order to allow motor run safely up to its limits. The Thermal Model is based mainly on currents, but it may be biased also by RTD and by Unbalance Currents.

This relay should protect the motor from abnormal conditions in the mains voltage, motor and cabling faults as well as operator malfunctions.

The MPS3000 monitors three phase voltages, three phase + ground fault currents, temperature inputs from up to 10 sensors, Four analog inputs and four programmable Discrete (Optically isolated logical) inputs. The MPS3000-C incorporates additional 16 discrete digital inputs.

The MPS3000 incorporates four programmable Analog Outputs as well as four programmable output change-over (form C) relays. One or more relays can be configured as Trip and / or Alarm. All inputs and outputs are combined to provide the most comprehensive protection package.

The MPS3000 can handle 52 different trips / alarms.

Voltage base protections	Under-voltage, Over-voltage, Phase-loss, Phase sequence, Maximum start time.
Current base protections	Too many starts, Under current, Load increase, Over-current level 1 (Stall/Locked protection), Over-current level 2 (Short circuit) Thermal Overload, Unbalanced current, Ground fault current.
Voltage/Current based protections	Under power, Low power factor.
Temperature based	Up to 10 sensors (10 RTDs are standard or optionally 6 RTDs + 4 thermistors).
General based protection	Control circuit fault (C only), Welded contact (C only), Three external faults, Comm. Port Failure.
Analog Inputs based protection	For external devices such as Vibration sensor.
Two levels for most faults	Usually used for Alarm and Trip.

Protection levels and time delay settings are individually configured using the key pad on the front panel or through communication.

Unique Tripping / Alarm options make it possible to program any fault as an Alarm, Trip, both or none. This unique facility also enables controlled fault Reset possibilities. Authorized key, extends the reset possibilities.
A unique calculated TIME TO TRIP feature allows the operator or host computer to take corrective actions before tripping.

2.2. Control Features

The MPS3000-C has the same functionality as the MPS3000 and also incorporates also control capabilities. It can control various starting methods like Direct Online, Star Delta, Soft Starters, Reversing and Two Speeds.

Twenty optically isolated logic inputs are used to enable many types of control: Local, remote (for PLC without serial link) or through RS485 serial link.

Two or three relays may be used to control DOL (direct online), Star/Delta, Soft-starters, Two Speed and Reversing -starting.

Throughout the entire document MPS3000–C information is written over a gray background. Please ignore this information for the MPS3000.

2.3. Supervision and Communication Features

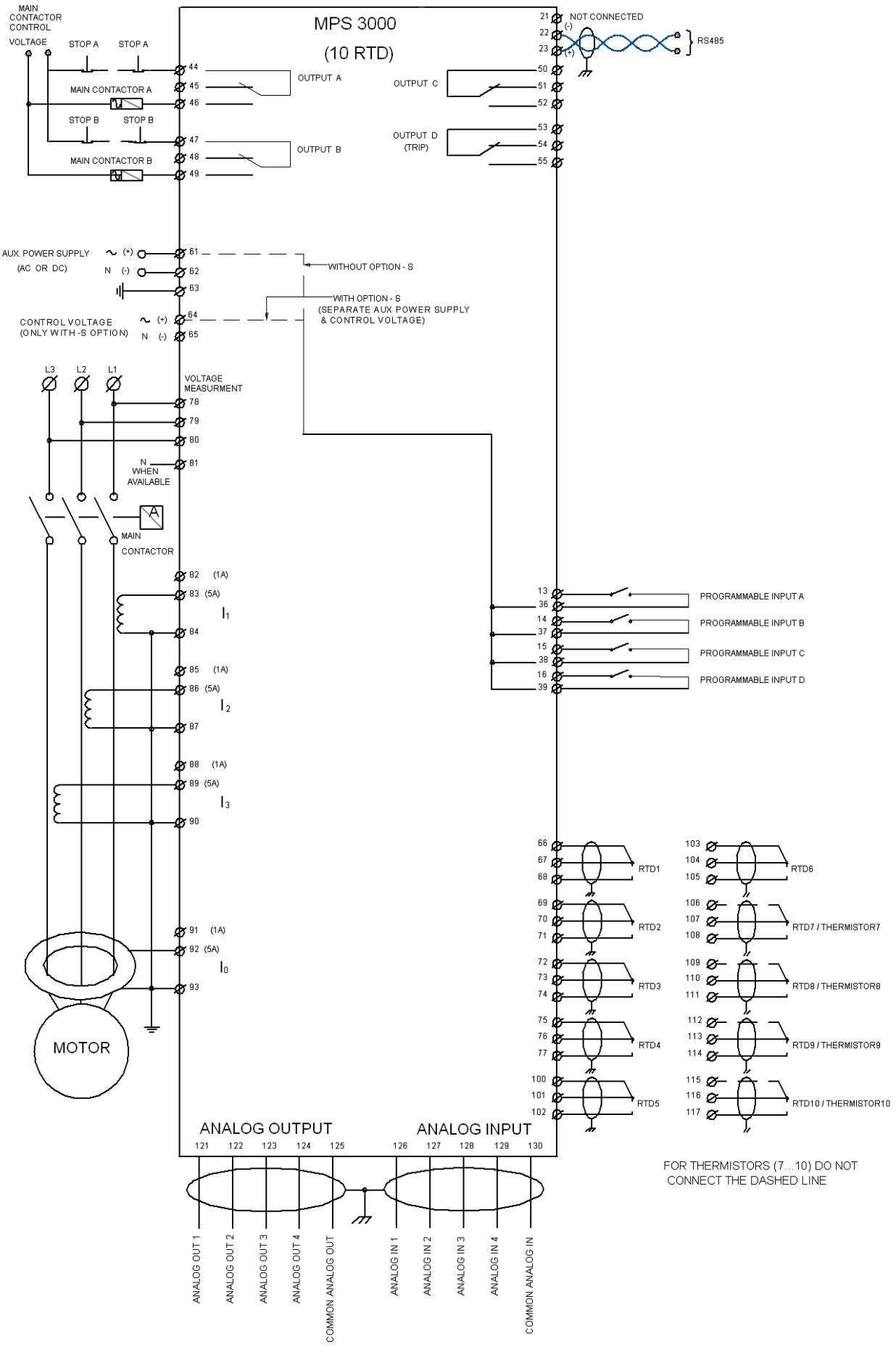
A Liquid Crystal Display (LCD), together with a keypad and LEDs enables user friendly interface, accurate digital parameters setting, actual parameters readings, and detailed trip and alarm message displays. Unauthorized setting changes can easily be prevented by the correct use of the Authorized key input terminals or a dedicated parameter: PARAM. SETTING (LOCKED or NOT LOCKED.

Measured data	Phase and line voltages, Phase currents, Ground fault current, Power, Reactive Power, Power factor, RTD temperatures (thermistor resistances) and Analog Inputs.
Calculated data	Motor load in % of FLC, Equivalent motor current, Unbalance current, Thermal Capacity, Time to trip, Time to start.
Logic inputs status	Individual status of all input contacts.
Statistical data	Motors running hours, Total number of starts, Total number of trips, Last start time, last start peak current, Total Energy, minimum and maximum values of voltage, current and frequency.
Fault data	Last Trip, Last Alarm, Phase currents at time of trip, Ground fault current at time of trip, Phase voltages at time of trip, last 10 faults with time and date stamp.
Fault Simulation –	Special Test / Maintenance page allows simulation (only during first 10 hours from auxiliary supply power up) by setting voltages currents and temperature “actual” values. The Simulation mode can be used for periodic testing of the relay. It can be used also for getting familiar with the MPS3000 modes of operation and features.

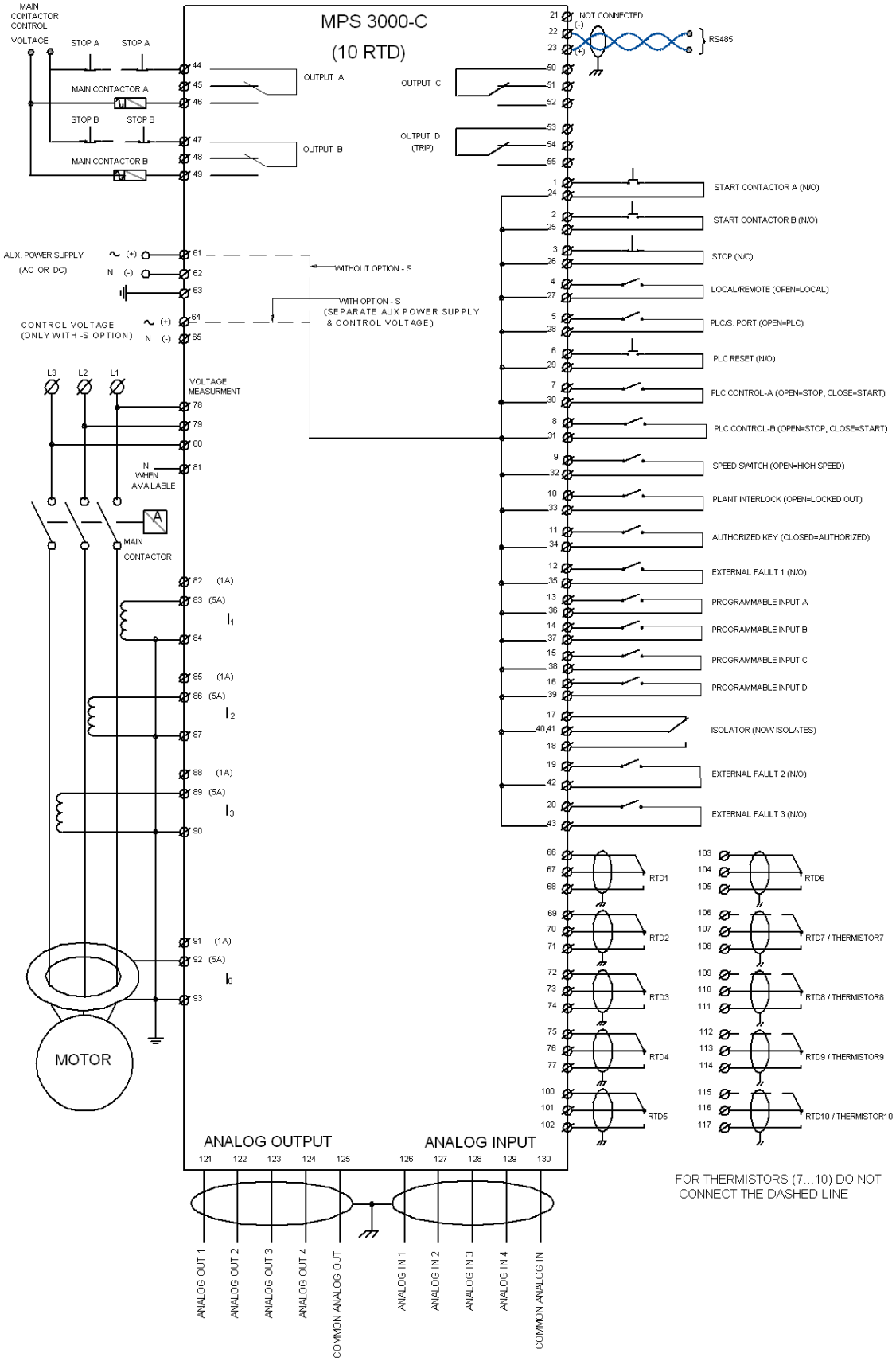
RS485 serial link (with MODBUS RTU communication protocol), operating at baud rate of 1200 to 38400 bps enables monitoring of both the "set page" and actual parameters. Changes of the "set page" parameters through the serial link make it very easy to enter user’s set points in place of the factory default parameters. The serial link enables remote control of both the MPS3000 and the motor.
RS485 enables 32 MPS3000 units to be connected on the same link to the host computer. When a need for more than 32 units arises, using MMI & Data highway equipment non limited number of MPS3000's can be connected to a host computer.

3. Wiring Diagrams

3.1. Wiring Diagram – MPS3000

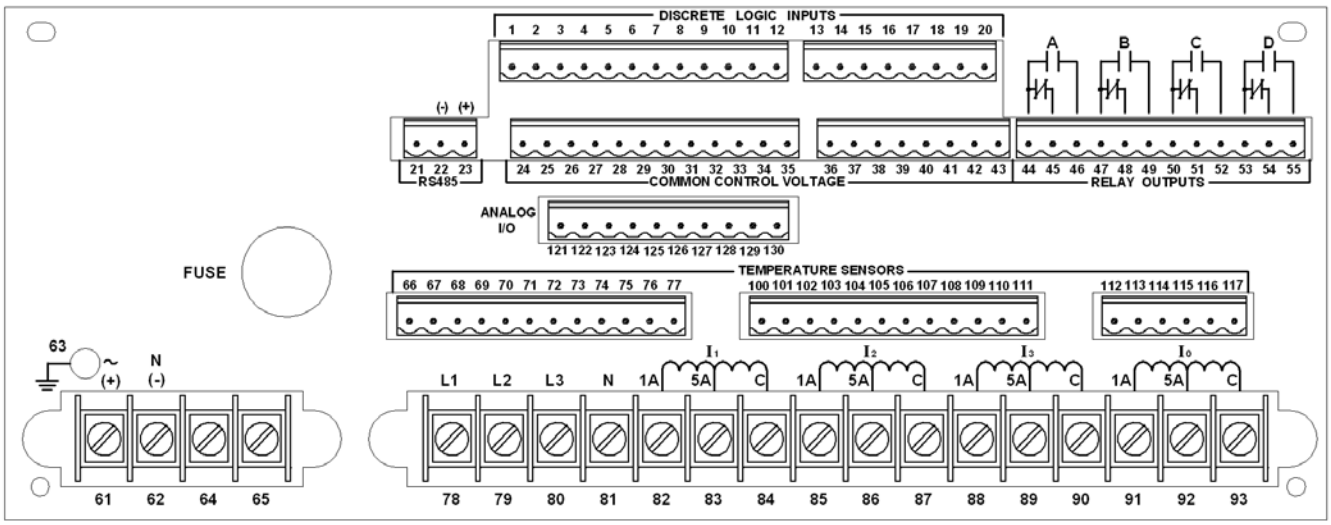


3.2. Wiring Diagram – MPS3000-C

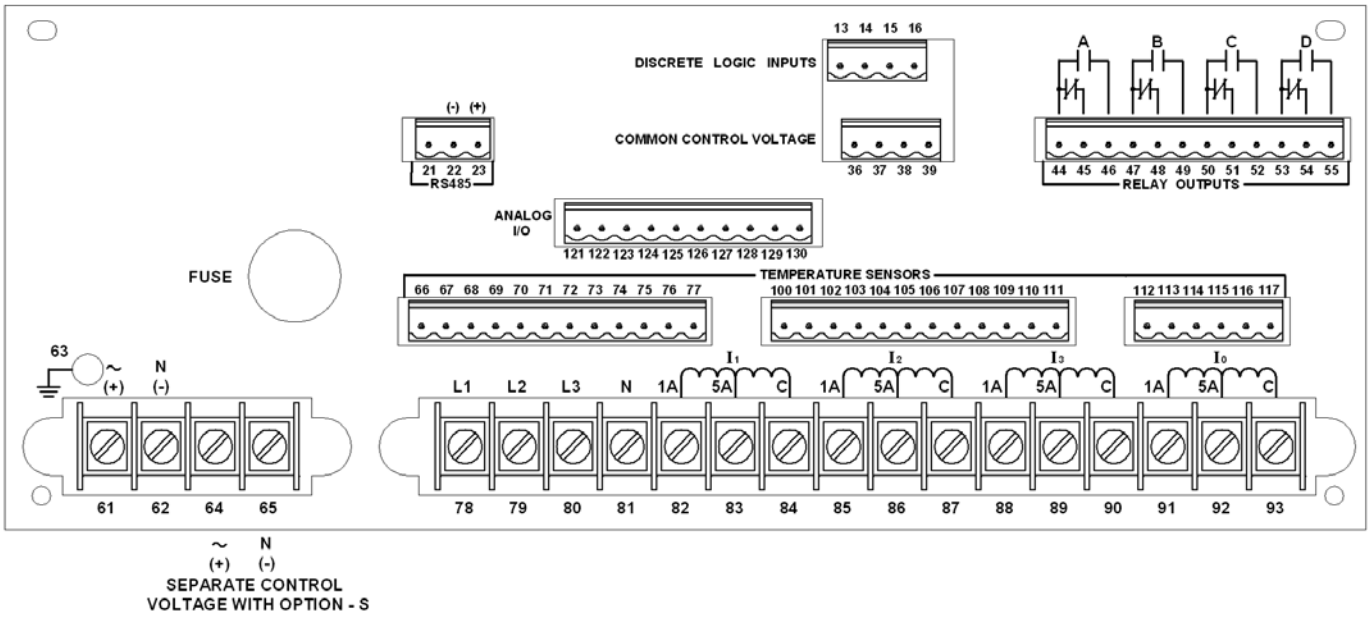


4. Rear Panel – MPS 3000 and MPS 3000-C

REAR PANEL FOR MPS 3000-C



REAR PANEL FOR MPS 3000



5. MPS 3000 Terminals

5.1. Auxiliary Power Supply

85…230VDC or AC (50/60) Hz

Phase or DC (+)……61
Neutral or DC (-)……62
Ground…… 63

With option (-S) for separate Aux. Power Supply and Control Voltage:
Phase or DC (+) 64
Neutral or DC (-) 65

5.2. Current & Voltage & Temperature (RTD, Thermistor) Inputs

The MPS3000 can measure: Three voltages analog inputs, four currents analog inputs and ten temperature sensors. True RMS measurement is used both for voltages and currents. Frequency should be in the range of 45-66 Hz. All current and voltage analog inputs incorporate internal isolating transformers.

5.3. Line Voltages

Direct connection of line to line voltages up to 690 VAC. For higher voltages, up to 25 KV, V/Ts must be used.

Voltage terminals are:

Phase L1 .....**78**
Phase L2 .....**79**
Phase L3 .....**80**
Neutral (when used)…..... **81**

Notes:

1. Line voltages must be connected for frequency sensing. If voltage analog inputs are not available, currents measurement is accurate only if frequency is 50Hz or 60Hz, as set.
2. For low voltage mains, all three phase voltages must be connected as shown in the wiring diagram.
3. For Medium and high voltage systems, when only a single V/T is used:
   - Connect V/T primary to mains V12 (“live” to V1 and “return” to V2).
   - Connect V/T secondary: “live” to phase voltage inputs (78, 79, and 80) and “return” to neutral input (81).
   - Decrease primary voltage setting by a 1.73 factor. In this type of connection, Line to Line voltage is connected to Line to Neutral input.
   - MPS3000 cannot detect phase sequence. A positive phase sequence is assumed.

For Medium and high voltage systems, when system voltage VTs are not available and AC power supply is used, connect auxiliary power supply (61) to phase voltage inputs (78,79, 80) and (62) to neutral input (81).

5.4. Line Currents

Currents measured through C/T secondary of 5 A or 1 A.

Phase L1 ... **1A, 5A, Comm.** **82, 83, 84**
Phase L2 ... **1A, 5A, Comm.** **85, 86, 87**
Phase L3 ... **1A, 5A, Comm.** **88, 89, 90**

Note: Power and Power Factor can be calculated only if three voltage inputs and three current inputs are applied to the MPS3000.

5.5. Ground Fault Current

Currents measured through a differential C/T with a secondary of 5 A or 1A.

All phases..**1A, 5A, COMM..**..... **91, 92, 93**

Note: It is recommended to use Core Balance C/T. If a Core Balance C/T is not available, Ground Fault can be measured according to C/T Wiring Diagrams on section 6.2 Page 15.

5.6. Temperature Sensors

The MPS3000 can accept inputs from Up to 10 RTDs of the following types:

- Copper 10 Ohm
- Platinum 100 Ohm
- Nickel 120 Ohm

LCD display is in °C (Refer to resistance/temperature table on page 47).

Notes:

1. All sensors must be of same type.
2. An optional unit with 6 RTDs and 4 thermistors (No. 7...No. 10) is available.

RTDs three wire measurement system is used to compensate for cable resistance. (max. cable resistance allowed is 25% of sensor resistance at 0°C). Only two wires are used for thermistor.

T1 ..... **66+67, 68**
T2 ..... **69+70, 71**
T3 ..... **72+73, 74**
T4 ..... **75+76, 77**
T5 ..... **100+101, 102**
T6 ..... **103+104, 105**
T7 ..... **106+107, 108** (Leave 106 open for thermistor, see note 2 above)
T8 ..... **109+110, 111** (Leave 109 open for thermistor, see note 2 above)
T9 ..... **112+113, 114** (Leave 112 open for thermistor, see note 2 above)
T10 ..... **115+116, 117** (Leave 115 open for thermistor, see note 2 above)

Note: If Temp sensors are not used, leave all relevant terminals open. Disable all the relevant Trip and Alarms.

Twisted and Shielded cables must be used for all temperature inputs. Shield should be connected to Chassis Ground externally, near the MPS3000.

5.7. Analog Outputs

The MPS3000 incorporates four programmable analog outputs. Outputs type can be programmed to 4..20 mA or 0..20 mA. Load resistance should be less than 400Ω. The four outputs share one common point. 0..1 mA type is also available. Each output can be configured to represent one of twenty different parameters. Outputs are updated every 100mS. Range of parameter for each output is fully programmable.

Analog Out 1 ..... **121**
Analog Out 2 ..... **122**
Analog Out 3 ..... **123**
Analog Out 4 ..... **124**
Analog Out Common **125**

Note: The analog outputs electronics is isolated as one group together with the Analog inputs (and with the Temperature input) circuits. Please note that only one common connection (Ground) have to be used for the analog inputs and outputs. (The Temperature input wires are normally individually isolated, so they have no common connection).

Twisted and Shielded cable must be used for all analog outputs. Shield should be connected to Chassis Ground externally, near the MPS3000.

5.8. Analog Inputs

The MPS3000 incorporates four programmable analog Inputs. Each input can be individually programmed for 4..20 mA or 0..20 mA types. The four inputs share one common point. 0..1 model is available. A fault protection is assigned for each analog input. Level and time delay is adjustable for each input. Scan cycle time: 100mS.

Analog In 1 ..... **126**
Analog In 2 ..... **127**
Analog In 3 ..... **128**
Analog In 4 ..... **129**
Analog In Common **130**

Note: The analog inputs electronics is isolated as one group together with the Analog outputs (and with the Temperature input) circuits. Please note that only one common connection (Ground) have to be used for the analog inputs and outputs. (The Temperature input wires are normally individually isolated, so they have no common connection).

Twisted and Shielded cable must be used for all analog inputs. Shield should be connected to Chassis Ground externally, near the MPS3000.

5.9. MPS3000-C Discrete Inputs

Local Start-A ..... **1&24**
Close the contact to operate contactor A. Maintained or Momentary contacts can be used.

Local Start-B ..... **2&25**
Close the contact to operate contactor B. Maintained or Momentary contacts can be used.
Used for low speed of two speed motor and for reversing applications.
Leave open if not used.

Local Stop ..... **3&26**
Open the contact to stop the motor. Maintained or Momentary contacts can be used.
Note: Open contact override any other inputs and force stop condition

Local/Remote ..... **4&27**
Open - For Local control
Closed - For Remote control
When contact is open, Motor can be locally started by above Local Start-A or Local Start-B contacts.
For safety reasons, Local Stop is always active, even if Local/Remote contact is in Remote position.

PLC/Serial Port ..... **5&28**
Open - For PLC control
Closed - For Serial Port control
Operative only when Local/Remote input is in closed (Remote) position. Determines if control commands are accepted from PLC or Serial Port inputs.

PLC Reset ..... **6&29**
MPS3000 fault reset through momentary N.O contact.
(See default authorization table section 9.9.1 page 36)

PLC control-A ..... **7&30**
Maintained N.O contact
Open - To stop motor.
Closed - To operate contactor A and start the motor.

PLC Control-B ..... **8&31**
Maintained N.O contact.
Open - To stop motor.
Closed - To operate contactor B and start the motor. Used for low speed of two speed motor and for reversing applications.

Speed Switch ..... **9&32**
Open - indicating that motor minimum speed has been reached
Closed- indicating that motor minimum speed has not been reached.
Indicates that the motor is turning. Leave input open if speed switch is not used.

Plant Interlock .....**10&33**
Open - To prevent operation
Closed - To enable operation
Permits additional systems interlocking.
If not used, Contact MUST be closed.

Authorized Key ..... **11&34**
Open - Disabled
Closed - To enable the following:

Note: For MPS3000, any one of the four discrete inputs (terminals 13..16) can be configured as Authorized key.

* Change of parameters (through keyboard).
* Reset of any alarm/trip, regardless setting.
* Reset of the thermal capacity.
* Run self test.
* Store default settings.
* Reset and store of statistical data.

External Fault 1 ..... **12&35**
Open – Run Enable
Closed - Fault
If not used, disable Alarm and Trip for External fault 1 in the MPS3000 setting, (see tripping and alarm setting table section 9.9.4 page 48).

The following four logical inputs, Discrete Input A to Discrete Input D, are common to both MPS3000 and the MPS3000-C.
Discrete Input A contact ..... **13&36**
Discrete Input B contact ..... **14&37**
Discrete Input C contact ..... **15&38**
Discrete Input D contact ..... .**16&39**

Each of the above four discrete inputs can be configured for many applications. (like Emergency Restart, Low speed of two speed motor, Remote Reset and External Faults).

Isolator
Aux. contacts of a local Isolator switch. Prevents contactors operation when the isolator is open. Start is enabled Only if 17-40 is open and 18-41 is closed. (e.g. Isolator is closed).
N.C. ..... **17&40**
N.O. ..... **18&41**
If not used 18-41 must be closed.

External Fault 2 ..... **19&42**
Open - Run Enable
Closed - Fault
If not used, disable Alarm and Trip for External Fault 2 in the MPS3000 setting, (see tripping and alarm setting table section 9.9.4 page 48).

External Fault 3 ..... **20&43**
Open - Run Enable
Closed - Fault
If not used, disable Alarm and Trip for External Fault 3 in the MPS3000 setting. (see tripping and alarm setting table section 9.9.4 page 48).

5.10. Output Relays

The MPS3000 incorporates four output relays. Each has a C/O contact, rated 8 A / 250 VAC resistive, 2000 VA inductive.
The four relays can be configured for alarm, alarm fail-safe, trip, trip fail-safe, overload, earth (Ground) Fault, KWH pulses and also for external contactors control required for the MPS3000-C.
Note: When a relay is configured as an alarm Fail-Safe or trip Fail-Safe, the relay is immediately energized when the auxiliary power supply is connected to terminals 61 & 62. The following N.O and N.C. terminals are given for Non-Energized relays.

Output Relay A:
N.C ..... **44&45**
N.O ..... **44&46**
Relay A can be configured as an Alarm, Alarm Fail-Safe, Tripping / Alarm (where it can be set for any group of faults), # Of Starts Pre Alarm (can be used to prevent start which will cause Too Many Starts fault) , U/V start prevent or KWH pulse relay. See later for additional control functions used with the MPS3000-C.

Output Relay B:
N.C ..... **47&48**
N.O ..... **47&49**

Relay B can be configured as Trip, Trip Fail-Safe, Tripping / Alarm (where it can be set for any group of faults) or # Of Starts Pre Alarm, u/v Start Prevent or (I > 0) After Trip relay. See later for additional control functions used with the MPS3000-C. When configured as (I > 0) After Trip, it can be used to trip upstream breaker if current still flows after the MPS3000 has issued a Trip signal.

Output Relay C:
N.C ..... **50&51**
N.O .....**50&52**
Relay C can be configured as Alarm Fail-Safe, Alarm, Contactor A/B status, Start/Run and Running indication.
See later for additional control functions used with the MPS3000-C.

Output Relay D:
N.C ..... **53&54**
N.O .....**53&55**

Relay D can be configured as a Trip, Trip Fail Safe or Ready relay.
The relays can be configured to receive two isolated alarm signals and two isolated trip signals.

Note: When a relay is configured for Fail Safe operation, relay is energized when MPS3000 is powered and de-energized upon fault. Relay C is designed mainly to be used as an alarm fail-safe, to alarm constantly when the unit is not powered.

MPS3000-C special use:
The relays can be configured with contactors control functions which may be required, according to the control application.

Output A Relay:
Can be configured as one of:
* DOL starting
* Star period of Star-Delta starting
* Forward of a forward-reverse motor
* High speed of two-speed motor

Output B Relay:
Can be configured (by parameter setting) as one of the following functions:
* Delta period of Star/Delta starting
* Reverse of a forward-reverse motor
* Low speed of two-speed motor

Output C Relay:
Can be configured (by parameter setting) as one of the following functions:
* Contactor A status.
* Contactor B status.
* Start/Run - controls line contactor in Star-Delta starters.

5.11. Serial Link

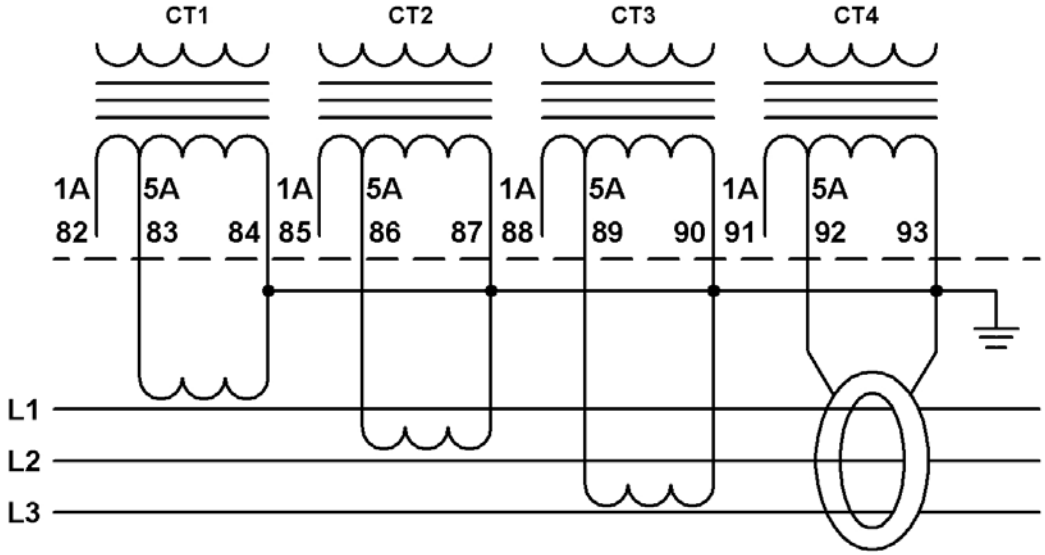
Standard RS485 Half Duplex, with MODBUS protocol.
Twisted shielded pair should be used for wiring. Shield should be connected to Chassis Ground externally, near the MPS3000.
Acceptable baud rates: 1200, 2400, 4800, 9600, 19200 and 38400 BPS.
Serial Port (+) **23**
Serial Port (-) **22**
Serial Port (shield) **63**
Notes:

1. Auxiliary Power Supply must power-cycled after changing communication's settings (e.g. baud-rate).
2. Connect 120 Ohm resistors between (+) and (-) at the end and at the beginning of the line.

6. C/Ts Wiring Diagrams

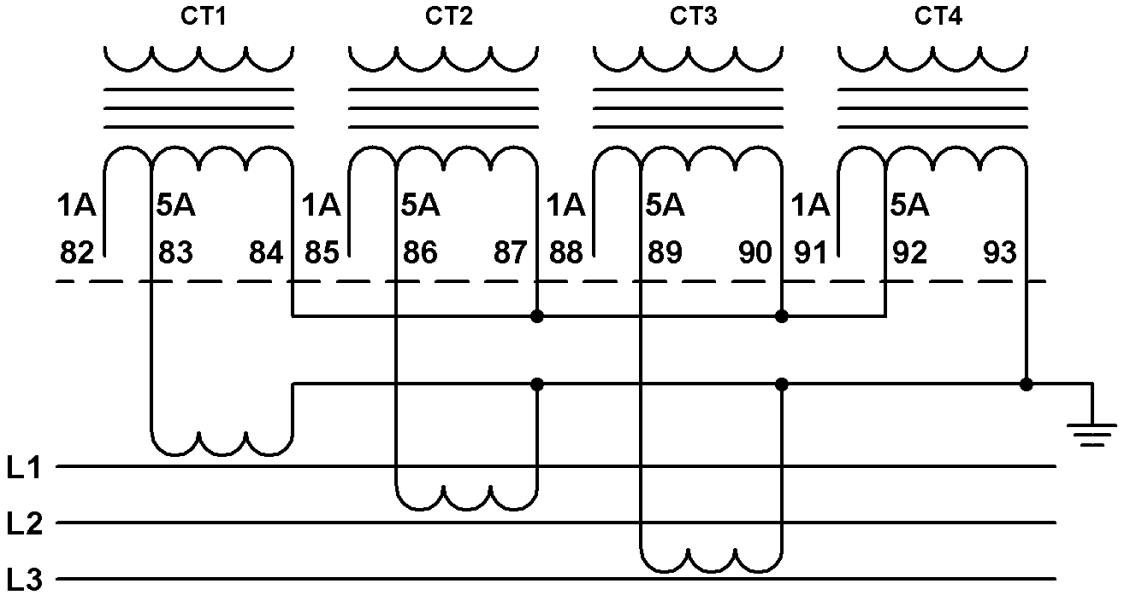
6.1. Three C/Ts + Ground Fault Core Balance C/T

It is the preferred connection. It drawback is that a relatively large Core Balance transformer is required.
In the following drawings, the 5A inputs are used and the 1A are left open.
In this diagram terminal 92 which is the Ground Fault input current gets the sum of the three phase currents. If there is no ground fault leakage current in the motor or cables, this current equals 0.



6.2. Three C/T's in a Residual Ground Fault Connection

When Core Balance C/T is not used and ground fault protection is required, use the residual Ground Fault Connection.
In this diagram terminal 92 which is the Ground Fault input current, receives the sum of the C/T outputs of the phase currents.
Ideally, if there is no ground fault leakage current, this current equals 0. Since C/Ts may saturate slightly during starting, their sum may not be 0 even when there is no leakage current to ground in the motor (or cables).
Note: In System Parameter page, the G/F DURING START setting parameter, is designed to significantly increase the G/F level, during starting (same level for alarm and for trip) to prevent nuisance alarming and / or tripping.
For Residual Connection, It is recommended to leave the value in its default value which is 100% of FLC**.**



7. Front Panel Overview and Settings

LEDs	
ON	ON when auxiliary power supply voltage is connected.
Stopped	ON in stop condition.
Starting	ON as a response to start command. Indicates that command is still "ON" and motor's average current is above 115% of rated current.
Running	ON after completion of starting process. Indicates that motor's average current decreased below 115% of rated current.
Output A	ON when Output A relay is energized.
Output B	ON when Output B relay is energized.
Alarm	ON indicates Alarm condition. Remains ON even if the alarm condition disappears, turns off only after resetting.
Trip	ON indicates Trip condition. Stays ON even if the trip condition disappears, turns off only after resetting.
Internal Fault	ON indicates internal fault detection. Stays lit even if internal fault disappears turns off after resetting.

LCD Display	
Two lines of 16 characters each	Used for display of all data and system messages.

Keys Overview	
Set Page	Press to change set parameter pages in positive cyclical order.
Data Page	Press to change the data page in positive cyclic order.
Select FWD	Press to forward parameters listed in this page. If key is pressed for more than 0.5 sec, parameters will be displayed at a fast rate.
Select REV	Press to reverse parameters listed in this page. If key is pressed for more than 0.5 sec, previous parameters will be displayed at a fast rate.
▲	Press once to increase parameter value. Press and hold to increase parameter value at a fast rate.
▼	Press once to decrease parameter value. Press and hold to decrease parameter value at a fast rate.
Reset	Press to Reset displayed Alarm or Trip
Store	Press to store displayed parameter value in the non-volatile memory.
	Note: If “Authorized Key” is locked out (open), only parameters viewing is possible. When the Key is closed, it is possible to view, change and store any set parameter.

7.1. Front Panel Settings

7.1.1. Startup

On startup the following occurs: **ON** and **Stopped** LED's are turned on
The LCD will display:

SYSTEM PARAMETER *** SETTINGS ***

In order to review above page settings, press **Select FWD.** key.
Messages are displayed on the LCD in two lines.
* Upper line describes the parameter's name.
* Lower line shows its value.
When **Authorized key** terminals are open, it is possible to view parameters but not to change or store them.
An attempt to change a value by ▲, ▼ or to store will result in UNAUTHORIZED ACCESS message.
To change settings, when **Authorized key** is closed, press▲ or ▼ keys and save the new value by pressing **Store** key. Once data was properly stored in the non-volatile memory the LCD displays the 2 Sec. flash message:

DATA SAVED OK

Notes:

1. A new parameter setting becomes effective **only** after storing it in the non-volatile memory. Setting a parameter, without storing, and moving to another parameter, will return the parameter to its previously stored value.
2. Any ***"set page"*** parameters can be viewed, altered and stored at any time. However, it is not recommended to change and store important parameters while the motor is starting or running.
3. Any stored parameter is kept indefinitely in the non-volatile memory.

7.1.2. Reset to Factory Default Values

Press Set Page key and ▼key simultaneously, the LCD will display:

TEST/MAINTENANCE *** OPTIONS ***

Press **Select FWD.** key three times, the LCD will display:

STORE NOW ? DEFAULT SETTINGS

Press **Store** and **Set Page** keys simultaneously, the LCD will display:

DATA SAVED OK

Note: Storing Default parameters erases all previously updated parameters

7.2. Messages

7.2.1. Blinking Messages

Blinking messages are displayed as a response to an event. For example:

DATA SAVED OK

The message is displayed for a short while (2 seconds) only. Display then returns to the previous message.
Blinking messages are usually displayed as a response to an operator action.
It is used either to confirm activation of the requested operation, or to indicate reason for not doing so.
The blinking messages are:

Display	Description
DATA SAVED OK	Displayed after pressing **Store** key. If an error is found during store process, then next message is shown.
STORAGE ERROR	Displayed when an error is found in the store process.
WRONG PARAMETERS	Displayed after power-up, if the non-volatile parameter check sum is found to be wrong.
UNAUTHORIZED ACCESS	When Authorized Key is open (locked), and a parameter change is attempted. Also displayed after Unauthorized

Display	Description
	Store and Reset action.
UNABLE TO START LOCAL / REMOTE	• Displayed if local Start is pressed but starting was not initiated because Local / Remote input is on Remote position. • Similar UNABLE TO START with another second line massage may appear specifying the real cause of the UNABLE TO START. • Possible cause: • LOCAL/REMOTE input = REMOTE. (PLC) • Local stop input is open (= stop). • U/V START PREVENT, prevents starting due to low voltage. • A trip is active. • External interlock = open (locked out) • Isolator status is "Isolate". • PROTECTION ONLY is set to YES. • Other reasons will cause CHECK SYSTEMS massage to appear in the second line.
SELF TEST PASSED	Displayed as a response to running the built in test procedure, provided that all tests were "O.K.".
SELF TEST FAILED ERROR CODE = 32	Displayed as a response to finding an error during the operation of Test procedure. In case of test failure, reset and test again. If problem persists then Error Code should be reported to Authorized Factory representative.

7.2.2. Solid Messages

Constant messages are displayed upon a fault. Example:

TRIP: MAX START TIME

Notes:

1. Pressing **Store** key while the LCD displays on "Data Page" or a "Set Page" parameter, will store this parameter as the default display. If no key is pressed for more than five minutes, then this parameter becomes the default display parameter. Same is correct for a Set Page header (first message of the page) display.

Constant messages are displayed, as a response to an event and not as a result of an operator action.

Display	Description
ALARM: U/C LEVEL 1	Displayed when the Alarm LED illuminates. The lower line displays the fault name.
TRIP: U/C LEVEL 2	Displayed when the Trip LED illuminates. The lower line displays the fault name.

7.3. Menu Navigation Top

7.3.1. SYSTEM PARAMETER SETTINGS

For parameter setting there are five menu options available.
By pressing **Set Page** key the LCD presents the following menus:

SYSTEM PARAMETER * SETTINGS *****	**OVERLOAD *** SETTINGS *****	**ANALOG I/O *** SETTINGS *****
VOLTAGE * SETTINGS *****	**POWER *** SETTINGS *****	**TRIPPING / ALARM *** OPTIONS *****
CURRENT * SETTINGS *****	**TEMPERATURE *** SETTINGS *****	**COMMUNICATION *** SETTINGS *****

7.3.2. MEASURED DATA

By pressing **Data Page** key the LCD displays the following headers:

MEASURED DATA - ** -**	**LOGICAL INPUTS - *CONTACT STATUS***	**FAULT DATA - **** -**
CALCULATED DATA - ** -**	**STATISTICAL DATA - **** -**	

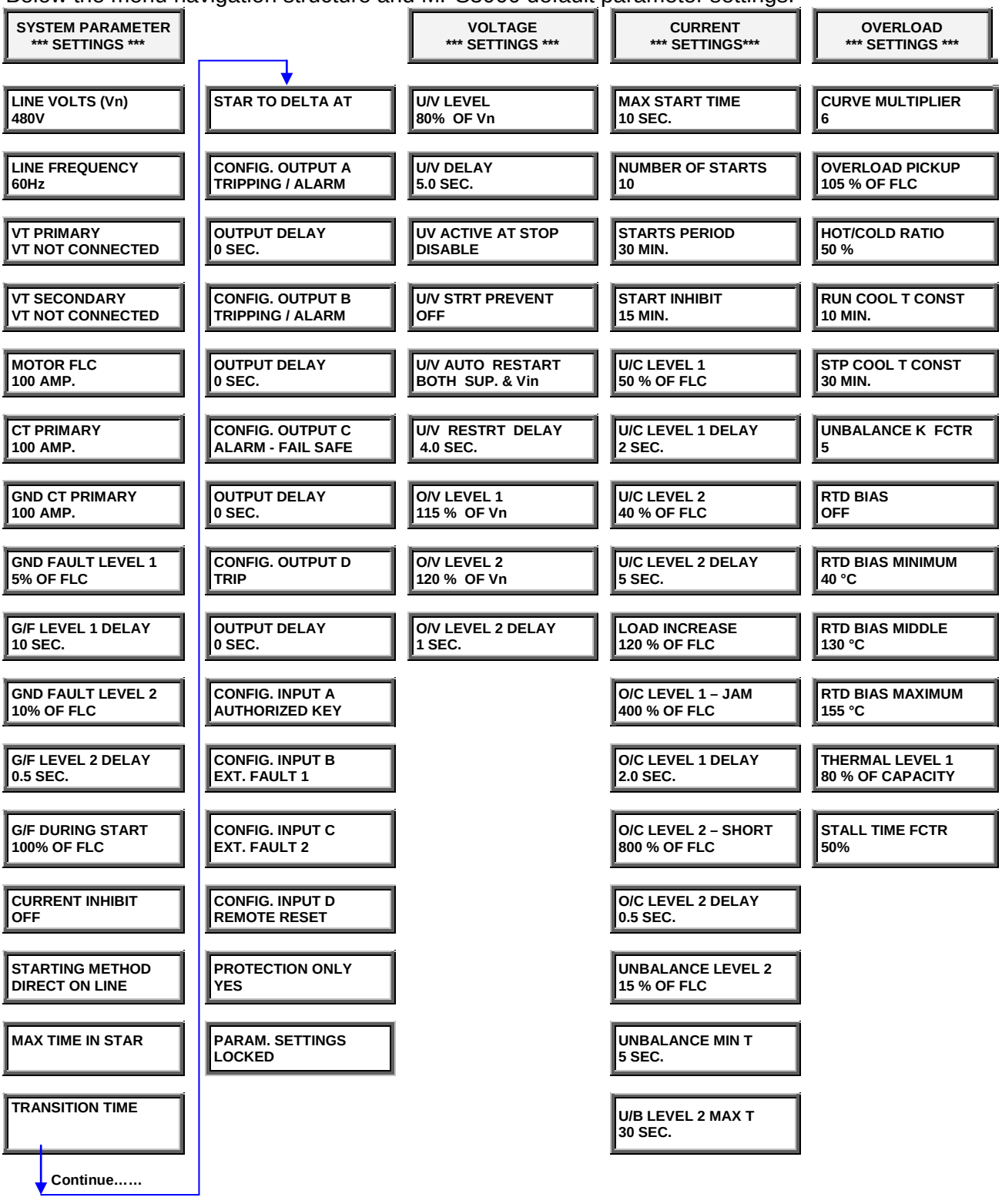
7.3.3. TEST / MAINTENANCE

By pressing **Set Page** key and ▼key simultaneously, the LCD will display:

TEST/MAINTENANCE * OPTIONS *****

8. Set Pages and Default Parameters

Below the menu navigation structure and MPS3000 default parameter settings.



POWER *** SETTINGS ***	TEMPERATURE *** SETTINGS ***	ANALOG I/O *** SETTINGS ***	TRIPPING / ALARM *** OPTIONS ***	COMMUNICATION *** SETTINGS ***
RATED PF AT FLC 0.88 LAG	RTD TYPE PLATINUM 100 OHM	ANALOG OUT TYPE 4..20mA	MAX START TIME TRIP: DISABLE	BAUD RATE 19200
UNDER PWR LEVEL 1 45%	SENSOR 7-10 TYPE RTD	ANLOG OUT 1 PAR. AVERAGE CURRENT	MAX START TIME ALARM: ENABLE	ADDRESS NUMBER OFF
U/P LEVEL 1 DELAY 30 SEC.	T1 LEVEL 1 120 °C	ANLOG OUT 1 MIN. 0 % OF FLC	MAX START TIME AUTO RST: DSABL	S.LINK PAR. SAVE DISABLE
UNDER PWR LEVEL 2 25%	T1 LEVEL 2 140 °C	ANLOG OUT 1 MAX. 200% OF FLC	MAX START TIME PANEL RST: ENABL	FRONT COM ADDRES OFF
U/P LEVEL 2 DELAY 30 SEC.	Same settings for RTD 2..6	ANLOG OUT 2 PAR. AVG. LINE VOLTS	MAX START TIME REMOT RST: ENABL	
LOW POWER FACTOR 0.8 LAG	T7 LEVEL 1 80 °C	ANLOG OUT 2 MIN. 0 % OF Vn	MAX START TIME OUTPUT A: DISABL	
LOW PF DELAY 30 SEC.	T7 LEVEL 2 100 °C	ANLOG OUT 2 MAX. 200% OF Vn	MAX START TIME OUTPUT B: DISABL	
KWH PER PULSE OFF	Same settings for RTD 8 & 9	ANLOG OUT 3 PAR. THERMAL CAPACITY	Similar settings for next 50 Fault protections Refer to table on Section 9.9.4 page 48.	
	T10 LEVEL 1 80 °C	ANLOG OUT 3 MIN. 0 % OF CAPACITY	. . . . .	
	T10 LEVEL 2 100 °C	ANLOG OUT 3 MAX. 200% OF CAPACITY	ANALOG INPUT # 4 TRIP: DISABLE	
	Note: If Sensor 7-10 are thermistors, then units of 7-10 are KΩ	ANLOG OUT 4 PAR. MAX OF T1..T3	ANALOG INPUT # 4 ALARM: DISABLE	
		ANLOG OUT 4 MIN. 0 °C	ANALOG INPUT # 4 AUTO RST: DSABL	
		ANLOG OUT 4 MAX. 200 °C	ANALOG INPUT # 4 PANEL RST: ENABL	
		ANALOG IN 1 TYPE 4..20 mA	ANALOG INPUT # 4 REMOT RST: ENABL	
		ANLOG IN 1 LEVEL ABOVE 50 %	ANALOG INPUT # 4 OUTPUT A: DISABL	
		ANLOG IN 1 DELAY 10 SEC.	ANALOG INPUT # 4 OUTPUT B: DISABL	
		Same settings for Analog in 2,3 & 4		

MEASURED DATA - **** -	CALCULATED DATA - **** -	LOGICAL INPUTS – CONTACT STATUS	STATISTICAL DATA - **** -	FAULT DATA - **** -
Vp1 Vp2 Vp3 230 230 230 V	MOTOR LOAD CURR. 96 % OF FLC	DISCRETE INPUT A CONTACT OPEN	TOTAL RUN TIME 9857 HOURS	LAST TRIP EXTERNAL FAULT 1
VL12 VL23 VL31 400 400 400 V	EQUIVALENT CURR. 97 % OF FLC	DISCRETE INPUT B CONTACT OPEN	TOTAL # OF START 410	LAST ALARM MAX START TIME
I1 I2 I3 100 101 100 A	UNBALANCE CURR. 5 %	DISCRETE INPUT C CONTACT OPEN	TOTAL # OF TRIPS 7	TRIP I1, I2, I3 431 435 432 A
GROUND CURRENT 0 AMP.	THERMAL CAPACITY 48 % OF CAPACITY	DISCRETE INPUT D CONTACT OPEN	LAST STRT PERIOD 9.8 SEC.	TRIP GND CURRENT 0 AMP.
FREQUENCY 50.0 Hz	TIME TO TRIP- O/L NO TRIP EXPECTED	Above fields are visible only if PROTECTION ONLY is set to Yes. If it is set to No, then status of motor, as well as status of all 20 inputs of MPS3000-C can be displayed.	LAST START MAX I 760 AMP.	TRIP Vp1, Vp2, Vp3 230 230 230 V
POWER 563.2 KW	TIME TO START 0 SEC.	MOTOR STATUS NOT AVAILABLE	TOTAL ENERGY 457,235 KWH	LAST 10 TRIPS:
REACTIVE POWER 601.3 KVAR		DISCRETE INPUT A CONTACT OPEN	TOTAL REACT. EN. 265,107 KVARH	EXTERNAL FAULT 1 08:32 08/05/02
POWER FACTOR 0.88		DISCRETE INPUT B CONTACT OPEN	MINIMUM VOLTAGE 395 VOLT	T1 LEVEL 2 13:33 06/13/02
T1 T2 T3 105 104 105 °C		DISCRETE INPUT C CONTACT OPEN	MAXIMUM VOLTAGE 404 VOLT	O / C LEVEL 2 –SHORT 11:26 03/21/02
T4 T5 T6 105 104 105 °C		DISCRETE INPUT D CONTACT OPEN	MINIMUM CURRENT 73 AMP.	Similar messages of previous 7 trips.
T7 T8 T9 80 85 ??? °C		EXTRNL INTERLOCK OPEN=LOCKED OUT	MAXIMUM CURRENT 86 AMP.	
T10 ??? °C		ISOLATOR N.O. OPEN=ISOLATED	MIN. FREQUENCY 49.9 Hz	
ANALOG INPUT # 1 20 %		ISOLATOR N.C. OPEN=RUN ENABLE	MAX. FREQUENCY 50.1Hz	
ANALOG INPUT # 2 20 %		START A INPUT CONTACT OPEN		
ANALOG INPUT # 3 20 %		START B INPUT CONTACT OPEN	PLC RESET CONTACT OPEN	
ANALOG INPUT # 4 20 %		STOP INPUT OPEN=STOP	SPEED SWITCH OPEN=HIGH SPEED	
		LOCAL/REMOTE OPEN=LOCAL	AUTHORIZED KEY OPEN=LOCKED	
		PLC CONTROL OPEN=PLC	EXTERNAL FAULT 1 OPEN=ENABLE	
		PLC CONTROL A OPEN=STOP	EXTERNAL FAULT 2 OPEN=ENABLE	
		PLC CONTROL B OPEN=STOP	EXTERNAL FAULT 3 OPEN=ENABLE	

Note: If Sensor 7-10 are thermistors, then units of T7-T10 are KΩ

Legend:

PLC CONTROL B
OPEN=STOP

Only displays in MPS 3000-C model and when PROTECTION ONLY is set to NO

9. PARAMETERS SETTINGS PAGES

These menus are accessed by pushing the SET PAGE button.

9.1. SYSTEM PARAMETER SETTINGS

SYSTEM PARAMETER
***** SETTINGS *****

Display	Description
LINE VOLTS (VN) **400 VOLT**	Rated Line to Line Mains Voltage. Range: 100V-22000V. Increments of : 1V
LINE FREQUENCY **50 HZ**	Rated Mains Frequency. Range: 50, 60 Hz
VT PRIMARY **VT NOT CONNECTED**	Primary voltage of mains Voltage Transformers. Transformer should be used for line voltages above 690V. Range: not connected, 100V-22000V. Increments of : 1V **Note**: When only one single phase VT is used, decrease VT PRIMARY voltage setting by 1.73 factor. Example: If mains voltage, line to line is 3300V and only one VT is used, set VT PRIMARY 3300/1.73 = 1900V. This is since Line voltage is converted to Phase voltage.
VT SECONDARY **VT NOT CONNECTED**	Secondary voltage of mains Voltage Transformer. Range: VT NOT CONNECTED, 95V - 660V. Increments of : 1V
MOTOR FLC **100 AMP.**	Motor Full Load (rated) Current. Range: 1 - 2000A. Increments of : 1A
C/T PRIMARY **100 AMP.**	Primary rated current of Current Transformer. (No need to set Secondary rated current). Range: 1 - 2000A. Increments of : 1A
GND C/T PRIMARY **100 AMP.**	Primary rated current of Ground Fault Transformer. (No need to set Secondary rated current). Range: 1 - 2000A. Increments of : 1A
GND FAULT LVL 1 **5% OF FLC**	Ground Fault current initiating a Level 1 Alarm / Trip (in % of Motor FLC), after G/F LEVEL 1 DELAY. This setting has no effect during starting. See G/F DURING START parameter here after. Range: 1 – 100% of FLC. Increments of : 1%
G/F LEVEL 1 DELAY **10 SEC.**	Ground Fault Level 1 Alarm / Trip Delay. Range: 1 - 60 Sec. Increments of : 1 Sec.
GND FAULT LVL 2 **10% OF FLC**	Ground Fault current initiating Level 2 Alarm / Trip (in % of Motor FLC),after G/F LEVEL 2 DELAY. This setting has no effect during starting. See G/F DURING START parameter here after. Range: 1-100% of Motor FLC. Increments of : 1 %.
G/F LEVEL 2 DELAY **0.5 SEC.**	Ground Fault Level 2 Alarm / Trip Delay. Range: 0 - 2 Sec. Increments of : 0.1 Sec.
G/F DURING START **100% OF FLC**	Ground Fault Level 1 & 2 Alarm / Trip During start period. Intended to be used with Residual C/Ts connection, to prevent nuisance tripping with high currents of start process. Range: 1 – 100% of FLC. Increments of: 1 %.

SYSTEM PARAMETER
***** SETTINGS *****

Display	Description
CURRENT INHIBIT OFF	Prevents trip signal to line contactor and inhibits opening of contactors A & B if used, when short circuit current exceeds the set value, to prevent contactor's damage. Thermal trip overrides current inhibit. Set to OFF when contactors are not used to trip the motor (for circuit breaker application). **WARNING**: The MPS will not protect the motor for high current above the current inhibit setting. It is the customers responsibility to ensure that the motor is protected for fault current, above CURRENT INHIBIT by external protection Range: OFF, 400-1000% of Motor FLC. Increments of: 10%.
STARTING METHOD DIRECT ON LINE	Type of starting method. Range: DIRECT ON LINE, STAR (WYE)/DELTA, REVERSING, TWO-SPEED, NO START PROCESS and TWO PHASE STARTR. Use NO START PROCESS setting, to allow entering to run even if current at “starting” is low (for example for transformer protection).

When selecting and storing STAR-DELTA method, the following three parameters values can be altered.

MAX. TIME IN STAR 10 SEC.	Time period during which star contactor is closed. This time will shorten if current decreases below STAR TO DELTA AT value, but not below 0.25 MAX TIME IN STAR. Range: 1- 60 Sec. Increments of : 0.1 Sec.
TRANSITION TIME 200 mSEC.	Time period when both contactors A and B are open. range: 0.05 - 2 Sec. Increments: 0.05 Sec.
STAR TO DELTA AT 150% OF FLC	Current value (in % of FLC) in which STAR TO DELTA switching occurs. Provided Star time is above 25% of MAX TIME IN STAR setting. Range: 70 - 200% of FLC. Increments of : 1%

When selecting and storing DIRECT ON LINE, REVERSING or TWO PHASE STARTR, none of the above parameters can be altered.
When selecting and storing TWO SPEED method, the following two parameters can be altered.

LOW SPEED FLC. 10 AMP.	Low speed motor FLC. Range: 1 - 2000 Amp. Increments of : 1A
LO SPD CURVE MUL 15	Overload Trip Curve Multiplier. **Note**: Set to 1..15 !! Range: 1 - 15. Increments of : 1.
STAR TO DELTA AT	Can not be altered.
CONFIG. OUTPUT A TRIPPING/ALARM	Enables Configuration of Output A relay as: CONTACTOR A: Relay is used for controlling the contactor • ALARM • ALARM - FAIL SAFE • TRIPPING / ALARM: Relay operates by group of faults as set in Tripping/Alarm page. Refer to section 9.9.4 page 48. • # STRTS PRE ALARM • U/V STRT PREVENT • KWH. PULSE RELAY • COMM. FORCING: Relay is controlled via communication
OUTPUT DELAY 0 SEC.	Time delay for Output A. Range: 0 - 250 Sec. Increments of : 1 Sec.

SYSTEM PARAMETER
***** SETTINGS *****

Display	Description
CONFIG. OUTPUT B TRIPPING/ALARM	Enables Configuration of Output B relay as: • CONTACTOR B: Relay is used for controlling the contactor • TRIP • TRIP - FAIL SAFE • TRIPPING / ALARM: Relay operates by group of faults as set in Tripping/Alarm page. Refer to section 9.9.4 page 48. • # STARTS PRE ALARM • U/V STRT PREVENT • (I > 0) AFTER TRIP: Can be used to trip an upstream breaker if contactor is welded • COMM. FORCING: Relay is controlled via communication
OUTPUT DELAY 0 SEC.	Time delay for Output B. Range: 0 - 250 Sec. Increments of : 1 Sec.
CONFIG. OUTPUT C ALARM- FAIL SAFE	Enables Configuration of Output C relay as: • ALARM - FAIL SAFE • ALARM • CONTACTOR A N.O.: Relay follows actual contactor A Status. To use, connect contactor A N.O. to Input B and set CONFIG. INPUT B as CONTACTOR A N.O. • CONTACTOR B N.O.: Relay follows actual contactor B Status. To use, connect contactor B N.O. to Input D and set CONFIG. INPUT D as CONTACTOR B N.O. • START / RUN: Relay shows that motor is in starting or running mode. Can be used for activating Start/Run (main) contactor of a Star-delta starter. • RUNNING: Running indication. Relay is activated after motor is started and current is reduced below 110% of OVERLOAD PICKUP level. • COMM. FORCING: Relay is controlled via communication
OUTPUT DELAY 0 SEC.	Time delay for Output C. Range: 0 - 250 Sec. Increments of : 1 Sec.
CONFIG. OUTPUT D TRIP	Enables Configuration of Output D relay as: • TRIP • TRIP - FAIL SAFE • READY: Indicates that the MPS3000 is not in protection only mode, There is no active trip, isolator switch is closed, interlock is not locked out, stop input is closed and voltage level is above the preset U/V Start Prevent. **Note**: Voltage level is checked only if motor is not already running. • COMM. FORCING: : Relay is controlled via communication
OUTPUT DELAY 0 SEC.	Time delay for Output D. Range: 0 - 250 Sec. Increments of : 1 Sec.

SYSTEM PARAMETER
***** SETTINGS *****

Display	Description
CONFIG. INPUT A AUTHORIZED KEY	Enables Configuration of Discrete Input A as: • CONTACTOR A N.C. (for MPS3000-C, for sensing contactor A status). • AUTHORIZED KEY • LOW SPD OF 2 SPD motor (for different FLC and Thermal Overload Curve). • EMERGENCY RESTRT (Reset Thermal capacity at stop, Ignore No. Of Starts). • EXTERNAL FAULT 1 (N.O., close to trip) • EXTERNAL FAULT 2. (N.O., close to trip) • EXTERNAL FAULT 3. (N.O., close to trip) • REMOTE RESET. • SPEED SWITCH (No Turn sensing, to engage Thermal Overload Stall Time Factor). • COMM. READING – Input A status is read/monitored via communication.
CONFIG. INPUT B EXTERNAL FAULT 1	Enables Configuration of Discrete Input B as: • CONTACTOR A N.O. (for MPS3000-C, for sensing contactor A status). • All Other settings as in CONFIG. INPUT A
CONFIG. INPUT C EXTERNAL FAULT 2	Enables Configuration of Discrete Input C as: • Contactor B N.C. (for MPS3000-C, for sensing contactor B status). • All Other settings as in CONFIG. INPUT A
CONFIG. INPUT D REMOTE RESET	Enables Configuration of Discrete Input D as: • Contactor B N.O. (for MPS3000-C, for sensing contactor B status). • All Other settings as in CONFIG. INPUT A
PROTECTION ONLY YES	Determines MPS operation mode: Protection & Control (no); Protection Only (yes) Range: YES, NO
PARAM.SETTINGS LOCKED	Can be used instead of external “Authorized Key” inputs. When set as LOCKED external key options function normally. When set as NOT LOCKED, external key inputs are ignored and MPS is in Authorized condition (same as if external key is connected). Range: LOCKED, NOT LOCKED

9.2. VOLTAGE SETTINGS

VOLTAGE
***** SETTINGS *****

Display	Description
U/V LEVEL **80% OF Vn**	Under Voltage level, (in % of nominal voltage). Fault occurs when voltage is below set value for more than U/V DELAY. Range: 50 - 95 % of Vn. Increments of : 1 %
U/V DELAY **5.0 SEC.**	Under Voltage time delay. Range: 0.2 - 10 Sec. Increments of : 0.1 Sec.
UV ACTIV AT STOP **DISABLE**	Determines if Under Voltage protection is active at stop. If disabled, u/v is active only if not at stop. Range: DISABLE, ENABLE
U/V STRT PREVENT **OFF**	Prevents starting if mains voltage is lower than set by U/V START PREVENT. For MPS3000-C only. Range: OFF, 51-95 % of Vn. Increments of : 1%
U/V AUTO RESTART **DISABLE**	ENABLES / DISABLES the auto Restart features. • Set to DISABLE, if Restart is not required. • Set to MEASURED VOLTAGE, if control power supply (61-62) is stable during mains failure (powered from UPS or DC). Mains Failure is detected and causes motor stop, when voltage decreases below 65% of rated voltage. Mains restoration is detected when voltage increases to above 85% of rated voltage. • Set to BOTH SUP & VIN for normal AC mains (both measured voltage (35,37) and control power supply (61,62) turn off during mains failure). **Note**: Setting as AUXILIARY SUPPLY may not cause restart, for mains failure duration of less than 0.5sec. Restart occurs only if: • Motor was Starting/Running before mains failure • Turn off time is 0.1 - 4 sec. (±25%) Range: DISABLE, AUXILIARY SUPPLY, MEASURED VOLTAGE, BOTH SUP. & VIN
U/V RESTART DELAY **4 SEC.**	Time delay for the auto Restart feature, counted from mains (auxiliary supply or measured voltage, as set on u/v Start Prevent) restoration Range: 0.4 – 25 Sec.
O/V LEVEL 1 **115% OF Vn**	Over Voltage Level 1. Fault occurs when voltage is above set value for more than 1 second (fixed delay). Range: 100 - 120 % of Un. Increments of : 1%
O/V LEVEL 2 **120% OF Vn**	Over Voltage Level 2. Fault occurs when voltage is above set value for more than O/V LEVEL 2 Delay. Range: 100 - 120 % of Un. Increments of : 1%
O/V LVL 2 DELAY **1 SEC.**	Over Voltage Level 2 delays. Range: 1 - 100 Sec. Increments of : 1Sec.

9.3. CURRENT SETTINGS

CURRENT
***** SETTINGS *****

Display	Description
MAX START TIME **10 SEC.**	Maximum Permitted starting time until current is reduced to 110% of Overload Pickup setting parameter. Protects the motor against too long starting. Range: 1 – 250 Sec. Increments of : 1 Sec.
NUMBER OF STARTS **10**	Maximum Permitted number of starts during STARTS PERIOD. Range: 1 – 10. Increments of : 1
STARTS PERIOD **30 MIN.**	Time period during which the NUMBER OF STARTS is counted. Range: 1 - 60 min. Increments of : 1 min.
START INHIBIT **15 MIN.**	Time period after which auto reset is prevented (even if enabled) after TOO MANY STARTS trip. Range: 1 - 60 min. Increments of: 1 min.
U/C LEVEL 1 **50% OF FLC**	Under Current Level 1. Fault occurs when current is below the set parameter for more than U/C LEVEL 1 DELAY. Range: 10 - 90 % of Motor FLC. Increments of : 1%
U/C LVL 1 DELAY **2 SEC.**	Under Current Level 1 Delay. Range: 1 - 60 Sec. Increments of : 1 Sec.
U/C LEVEL 2 **40% OF FLC**	Under Current Level 2. Range: 10 - 90 % of Motor FLC. Increments of : 1%
U/C LVL 2 DELAY **5 SEC.**	Under Current Level 2 Delay. Range: 1 - 60 Sec. Increments of : 1 Sec.
LOAD INCREASE **120% OF FLC**	Fault occurs when current is above the set parameter for more than fixed time period of 5 seconds. Range: 60 - 150% of Motor FLC. Increments of : 1%
O/C LEVEL 1- JAM **400 % OF FLC**	Over Current Level 1- Jam (stall) protection. Operative after start process ended. Indicates that current exceeded set value for more than O/C LEVEL 1 DELAY. Range: 100 - 500 % of Motor FLC. Increments of : 10%
O/C LVL 1 DELAY **2.0 SEC.**	Time delay for O/C Level 1. Range: 0.5 - 10 Sec. Increments of : 0.1 Sec.
O/C LVL 2- SHORT **800 % OF FLC**	Over Current Level 2- Short circuit protection. Operative during starting and running. Indicates that current exceeded set value for more than O/C LEVEL 2 DELAY. Range: 400 - 1200 % of Motor FLC. Increments of : 10%
O/C LVL 2 DELAY **0.5 SEC.**	Time delay for Over Current Level 2 **Note**: When set to 0, actual delay is less than 70mSec. Range: 0 - 4 Sec. Increments of : 0.1 Sec.

CURRENT
***** SETTINGS *****

Display	Description
UNBALANCE LVL 2 **15 % OF FLC**	Unbalance Current. Fault occurs only if actual Unbalance is greater than the set value. **Note** - Unbalance Current level 1 will be activated when Unbalance Current exceeds 50% of the UNBALANCE LEVEL 2 for more than 1 second (fixed time period). Range: 10 - 40 % of Motor FLC. Increments of : 1%
UNBALANCE MIN T **5 SEC.**	Unbalance Minimum response time for both Alarm and Trip. Range: 1 - 30 Sec. Increments of : 1 Sec.
U/B LVL 2 MAX T **30 SEC.**	Unbalance curve selection. Time delay at 10% of Unbalance. Fault time is inversely related to the actual unbalance (See Figure 3 – Unbalance Protection Time Delay, page 44). Range: 20 - 120 Sec. Increments of : 1 Sec.

9.4. OVERLOAD SETTINGS

OVERLOAD
***** SETTINGS *****

Display	Description
CURVE MULTIPLIER **6**	Overload Curve Multiplier. Shifts the entire Overload Curve. Range: 1 - 15. Increments of : 1.
OVERLOAD PICKUP **105% OF FLC**	Lower threshold for O/L protection. Below this threshold, O/L fault cannot occur. Range: 60 - 130 % of Motor FLC. Increments of : 1%
HOT/COLD RATIO **50%**	The ratio between thermal Capacity available for starting a hot motor and thermal capacity available for starting a cold motor. (A higher setting allows for a longer starting time of hot motor before tripping). Range: 20- 100% of Thermal Capacity. Increments of: 1%.
RUN COOL T CONST **10 MIN.**	Cooling Time Constant while motor is running. When Current is smaller than Overload Pickup, Thermal Capacity is exponentially reduced to simulate motor cooling to (100-Hot/Cold ratio) Range: 1 – 240 min. Increments of: 1min.
STP COOL T CONST **30 MIN.**	Cooling Time Constant while motor is stopped. This time constant is normally significantly longer than the Cooling Time Constant of a running motor. Range: 1 – 240 min. Increments of: 1min.
UNBALANCE K FCTR **5**	Unbalance K Factor. Used to increase the motor's equivalent current as a result of Unbalance currents. The Unbalance currents cause a negative Sequence Currents. The MPS3000 measures the Negative as well as positive sequence currents and uses their values to calculate the equivalent current, given by: $LEQ = I\% * \sqrt{(1 + K * (I_2/ I_1)^2)}$ Where: **I%** - Motor RMS (average of the three phases) current I_2 – Negative sequence Current I_1 – Positive Sequence current Range: 0 – 15. Increments of: 1

OVERLOAD
***** SETTINGS *****

Display	Description
RTD BIAS **OFF**	RTD Bias allows to disable RTD Bias, to use max of RTD1..3 or to use max of RTD1..6 for the temperature bias. Note that when enabled, the RTD BIAS can only increase the Thermal Capacity value. It can never decrease it. Range: OFF, T1..T3, T1..T6
RTD BIAS MINIMUM **40 °C**	RTD Minimum is the minimum bias temperature. Below this temperature, the RTD bias has no effect on the thermal model. Range: 10°C..RTD BIAS MIDDLE. Increment of: 1°C.
RTD BIAS MIDDLE **130 °C**	Set RTD Middle to the normal expected working temperature with 100% load. At this point, the thermal capacity (at steady state) should be 100 – Hot/Cold ratio. Range: RTD MINIMUM…RTD MAXIMUM. Increment of: 1°C.
RTD BIAS MAXIMUM **155 °C**	Set RTD Max to the maximum allowed working temperature. At this point, the thermal capacity should be 100%. Range: RTD MIDDLE…250°C. Increment of: 1°C.
THERMAL LEVEL 1 **80% OF CAPACITY**	Thermal Capacity level 1. Normally used for alarm indication. Range: 50 - 99 % of maximum thermal capacity. Increments of : 1%
STALL TIME FCTR **50%**	Stall Time Factor. The ratio between motor thermal time constant when speed switch is closed (indicating slow speed) to thermal time constant with open speed switch - (indicating high speed). Operative when speed switch is used. Range: 20 - 100 %. Increments of: 1%

9.5. POWER SETTINGS

POWER
***** SETTINGS *****

Display	Description
RATED PF AT FLC **0.88 LAG**	Motor rated (Nameplate) power factor. Required for calculating rated power (based on motor FLC and line volts). Range: 0.5 – 0.99. Increment of : 0.01
UNDER PWR LVL 1 **45%**	Under power level 1.In percent of rated power, calculated by: √3 * Line Volts * Motor FLC * RATED POWER FACTOR Range: 5 - 99%. Increment of : 1%
U/P LVL 1 DELAY **30 SEC.**	Under Power Level 1 time delay. Range: 1 - 120 Sec. Increment of : 1 Sec.
UNDER PWR LVL 2 **25%**	Under power level 2, in percent of rated power. Range: 5 - 99%. Increment of : 1%
U/P LVL 2 DELAY **30 SEC.**	Under Power Level 2 time delay. Range: 1 - 120 Sec. Increment of : 1 Sec.
LOW POWER FACTOR **0.80 LAG**	Low Power factor level. Fault occurs when PF is below the set parameter for more than Low PF Delay. Range: 0.20 - 0.98. Increment of: 0.01
LOW PF DELAY **30 SEC.**	Low Power Factor Delay Range: 1 – 120. Increment of: 1
KWH PER PULSE **OFF**	KWH pulse relay. Set required KWH for each relay pulse. Range: OFF, 1 – 100. Increment of: 1

9.6. TEMPERATURE SETTINGS

TEMPERATURE
***** SETTINGS *****

General Note: Fault occurs when temperature is above the set parameter for more than a fixed time period of 2 seconds

LEVEL 1 & 2 FAULT

Display	Description
RTD TYPE	Resistance Temperature Detector Type.
PLATINUM 100 OHM	Range: Copper 10 Ohm, Platinum 100 Ohm, Nickel 120 Ohm
SENSOR 7-10 TYPE	Type of sensors T7..T10. MPS3000 can be ordered with T7..T10 measurement circuits designed
RTD	for Thermistors instead RTD.
	Range: RTD, PTC Thermistor, NTC Thermistor
T1 LEVEL 1	RTD No. 1 level 1
120 °C	Range: 0 - 250 °C. Increment: 1 °C
T1 LEVEL 2	RTD No. 1 level 2.
140°C	Range: 0 - 250 °C. Increment: 1 °C
T2 LEVEL 1	RTD No. 2 level 1
120 °C	Range: 0 - 250 °C. Increment: 1 °C
T2 LEVEL 2	RTD No. 2 level 2
140 °C	Range: 0 - 250 °C. Increment: 1 °C
T3 LEVEL 1	RTD No. 3 level 1
120 °C	Range: 0 - 250 °C. Increment: 1 °C
T3 LEVEL 2	RTD No. 3 at level 2
140 °C	Range: 0 - 250 °C. Increment: 1 °C
T4 LEVEL 1	RTD No. 4 level 1
120 °C	Range: 0 - 250 °C. Increment: 1 °C
T4 LEVEL 2	RTD No. 4 level 2
140 °C	Range: 0 - 250 °C. Increment: 1 °C
T5 LEVEL 1	RTD No. 5 level 1
120 °C	Range: 0 - 250 °C. Increment: 1 °C
T5 LEVEL 2	RTD No. 5 level 2
140 °C	Range: 0 - 250 °C. Increment: 1 °C
T6 LEVEL 1	RTD No. 6 level 1
120 °C	Range: 0 - 250 °C. Increment: 1 °C
T6 LEVEL 2	RTD No. 6 level 2
140 °C	Range: 0 - 250 °C. Increment: 1 °C
T7 LEVEL 1	RTD (or Thermistor) No. 7 level 1
80 °C	Range: 0 - 250 °C (or 25.0 KΩ). Increment: 1 °C (or 1/10 KΩ)
T7 LEVEL 2	RTD (or Thermistor) No. 7 level 2
100 °C	Range: 0 - 250 °C (or 25.0 KΩ). Increment: 1 °C (or 1/10 KΩ)
T8 LEVEL 1	RTD (or Thermistor) No. 8 level 1
80 °C	Range: 0 - 250 °C (or 25.0 KΩ). Increment: 1 °C (or 1/10 KΩ)
T8 LEVEL 2	RTD (or Thermistor) No. 8 level 2
100 °C	Range: 0 - 250 °C (or 25.0 KΩ). Increment: 1 °C (or 1/10 KΩ)
T9 LEVEL 1	RTD (or Thermistor) No. 9 at level 1
80 °C	Range: 0 - 250 °C (or 25.0 KΩ). Increment: 1 °C (or 1/10 KΩ)
T9 LEVEL 2	RTD (or Thermistor) No. 9 level 2
100 °C	Range: 0 - 250 °C (or 25.0 KΩ). Increment: 1 °C (or 1/10 KΩ)
T10 LEVEL 1	RTD (or Thermistor) No. 10 level 1
80 °C	Range: 0 - 250 °C (or 25.0 KΩ). Increment: 1 °C (or 1/10 KΩ)
T10 LEVEL 2	RTD (or Thermistor) No. 10 level 2
100 °C	Range: 0 - 250 °C (or 25.0 KΩ). Increment: 1 °C (or 1/10 KΩ)

9.7. ANALOG I/O SETTINGS

ANALOG I/O
***** SETTINGS *****

Display	Description
ANALOG OUT TYPE 4..20MA	Selects between 0..20 mA (or 0..1mA by special order) and 4..20 mA analog outputs (all four). This parameter is common for all four Analog Outputs. Range: 0..20 mA or 4..20mA.
ANLOG OUT 1 PAR. AVERAGE CURRENT	Analog 1 output parameter. Following parameters can be selected: • **I1:** RMS current of phase 1, % of motor FLC. • **I2:** RMS current of phase 2, % of motor FLC. • **I3:** RMS current of phase 3, % of motor FLC. • **AVERAGE CURRENT:** Average (RMS) of: I1, I2, I3. % of motor FLC. • **MAX OF: I1, I2, I3**: Maximum (RMS) of I1, I2, I3. % of motor FLC. • **GROUND CURRENT**: I0 (Ground fault RMS leakage current). % of motor FLC. • **V1**: Vp1 (Phase 1 to Neutral RMS Voltage). % of motor FLC. % of Rated Line Voltage. • **V2**: Vp2 (Phase 2 to Neutral RMS Voltage). % of motor FLC. % of Rated Line Voltage. • **V3**: Vp3 (Phase 3 to Neutral RMS Voltage). % of motor FLC. % of Rated Line Voltage. • **AVG. PHASE VOLTS:** Average (RMS) of Vp1, Vp2, Vp3. % of motor FLC. % of Rated Line Voltage. • **V12**: VL12 (Line 1 to Line 2 RMS Voltage). % of motor FLC. % of Rated Line Voltage. • **V23**: VL23 (Line 2 to Line 3 RMS Voltage). % of motor FLC. % of Rated Line Voltage. • **V31**: VL31 (Line 3 to Line 1 RMS Voltage). % of motor FLC. % of Rated Line Voltage. • **AVG. LINE VOLTS**: Average (RMS) of VL12, VL23, VL31. % of motor FLC. % of Rated Line Voltage. • **POWER**: Power, % of rated Power. • **POWER FACTOR**: Power Factor (*100). • **THERMAL CAPACITY**: Thermal Capacity, %. • **MAX OF T1…T3:** Max of T1, T2, T3. °C. • **MAX OF T4…T6:** Max of T4, T5, T6. °C. • **MAX OF T7…T9:** Max of T7, T8, T9. °C (or 1/10 KΩ for Thermistor). • **MAX OF T9…T10:** Max of T9, T10. °C (or 1/10 KΩ for Thermistor). • **ANLOG OUT 1 MAX.:** Analog out will track the value set in parameter ANALOG OUT 1 MAX. with an upper limit of 100%. (this feature mainly used for testing and maintenance)
ANLOG OUT 1 MIN. 0 % OF FLC	Value for zero (0 or 4mA) output. Range: 0..200 (Units change with parameter).
ANLOG OUT 1 MAX. 200 % OF FLC	Value for maximum (20mA, or 1mA by special order) output. Range: 0..250 (Units change with parameter).
ANLOG OUT 2 PAR. AVG. LINE VOLTS	Analog 2 output parameter. Range: Same as for ANALOG OUT 1 PAR.

ANALOG I/O
***** SETTINGS *****

Display	Description
ANLOG OUT 2 MIN. 0 % OF FLC	Value for zero (0 or 4mA) output. Range: 0..200 (Units change with parameter).
ANLOG OUT 2 MAX. 200 % OF FLC	Value for maximum (20mA, or 1mA by special order) output. Range: 0..250 (Units change with parameter).
ANLOG OUT 3 PAR. THERMAL CAPACITY	Analog 3 output parameter. Range: Same as for ANALOG OUT 1 PAR.
ANLOG OUT 3 MIN. 0 % OF FLC	Value for zero (0 or 4mA) output. Range: 0..200 (Units change with parameter).
ANLOG OUT 3 MAX. 200 % OF FLC	Value for maximum (20mA, or 1mA by special order) output. Range: 0..250 (Units change with parameter).
ANLOG OUT 4 PAR. MAX OF T1..T3	Analog 4 output parameter. Range: Same as for ANALOG OUT 1 PAR.
ANLOG OUT 4 MIN. 0 °C	Value for zero (0 or 4mA) output. Range: 0..200 (Units change with parameter).
ANLOG OUT 4 MAX. 200 °C	Value for maximum (20mA, or 1mA by special order) output. Range: 0..250 (Units change with parameter).
ANLOG IN 1 TYPE 4..20mA	Selects between 0..20mA (or 0..1mA by special order) and 4..20mA analog input type. Range: 0..20mA (0..1mA by special order), 4..20mA..
ANLOG IN 1 LEVEL. ABOVE 50%	Fault Level. Fault occurs when input is Above (or Below, if set so) Anlog In 1 Level for more than Anlog In 1 Delay. Range: Below 0..100%, Above 1..100%.
ANLOG IN 1 DELAY 10 SEC.	Time Delay for Analog Input 1 Fault. Range: 0..250 Sec.
ANLOG IN 2 TYPE 4..20mA	Selects between 0..20mA (or 0..1mA by special order) and 4..20mA analog input type. Range: 0..20mA (0..1mA by special order), 4..20mA..
ANLOG IN 2 LEVEL. ABOVE 50%	Fault Level. Fault occurs when input is Above (or Below, if set so) Anlog In 2 Level for more than Anlog In 2 Delay. Range: Below 1..100%, Above 1..100%.
ANLOG IN 2 DELAY 10 SEC.	Time Delay for Analog Input 2 Fault. Range: 0..250 Sec.
ANLOG IN 3 TYPE 4..20mA	Selects between 0..20mA (or 0..1mA by special order) and 4..20mA analog input type. Range: 0..20mA (0..1mA by special order), 4..20mA..
ANLOG IN 3 LEVEL. ABOVE 50%	Fault Level. Fault occurs when input is Above (or Below, if set so) Anlog In 3 Level for more than Anlog In 3 Delay. Range: Below 1..100%, Above 1..100%.
ANLOG IN 3 DELAY 10 SEC.	Time Delay for Analog Input 3 Fault. Range: 0..250 Sec.

ANALOG I/O
***** SETTINGS *****

Display	Description
ANLOG IN 4 TYPE 4..20mA	Selects between 0..20mA (or 0..1mA by special order) and 4..20mA analog input type. Range: 0..20mA (0..1mA by special order), 4..20mA..
ANLOG IN 4 LEVEL. ABOVE 50%	Fault Level. Fault occurs when input is Above (or Below, if set so) Anlog In 4 Level for more than Anlog In 4 Delay. Range: Below 1..100%, Above 1..100%.
ANLOG IN 4 DELAY 10 SEC.	Time Delay for Analog Input 4 Fault. Range: 0..250 Sec.

9.8. COMMUNICATION P. SETTINGS

COMMUNICATION P.
***** SETTINGS *****

Display	Description
BAUD RATE 19200 (MODBUS)	Serial Link communication speed in bps. Disconnect and then reconnect auxiliary supply after any change of baud rate. Range: 1200, 2400, 4800, 9600, 19200, 38400 bps.
ADDRESS NUMBER OFF	MPS Address on Serial Link. RS485 Allows a maximum of 32 MPS3000s on a twisted pair. Range: 1 - 247, 248 = OFF. Increments of: 1
S. LINK PAR. SAVE DISABLE	When set to DISABLE, prevents setting through serial link communication. When set to ENABLE, setting through serial link is enabled. Range: ENABLE, DISABLE
FRONT COM ADDRES OFF	When rear connection is used for Profibus communication link, front communication link can be used for setting parameters. Range: 1 - 247, 248 = OFF. Increments of: 1

Note: It is only possible to write and read through MODBUS communication (only !, parameters cannot be displayed on screen and cannot be changed from keyboard) 20 additional setting parameters. These parameters are numbers of MODBUS actual parameters. By writing to these parameters, user can define a group of up to 20 parameters that can be scanned as one group. See the MPS 3000-10 COMMUNICATION Manual for further reference.

9.9. TRIPPING/ALARM OPTIONS

TRIPPING / ALARM
***** OPTIONS *****

9.9.1. Tripping Alarm Common Settings

All MPS3000 protections share the same settings described below. Accessible via the menu Tripping/Alarm Options.

Area	Function	Setting	Observation
Mode	Trip only	Set Trip: ENABLE Set Alarm: DISABLE	Behavior upon Fault Trip LED illuminates. Output D relay: if configured as "Trip", energizes. If configured to "Trip - Fail Safe", de-energizes. Output A, Output B and Output C relays respond according to their configurations. Output A and Output B LEDs, displays the status of Output A & B relays.
Mode	Alarm only	Set Trip: DISABLE Set Alarm: ENABLE	Behavior upon Fault Alarm LED illuminates. Output A,B,C relays respond according to their configurations, Output A and Output B LEDs, displays the status of Output A & B relays.
Mode	Alarm and Trip	Set Trip: ENABLE Set Alarm: ENABLE	Behavior upon Fault Trip and Alarm LEDs illuminate. Output A,B,C,D relays respond according to their configurations, Output A and Output B LEDs, displays the status of Output A & B relays.
Mode	Disabled	Set Trip: DISABLE Set Alarm: DISABLE	Behavior upon Fault The MPS3000 completely ignores the fault.
Reset	Auto Reset	Set Auto Rst: ENABLE. (when not required set to DISABLE)	The MPS3000 resets itself automatically when the fault cause disappears. The Auto Reset is activated after a 2 second delay. It is recommended to always Disable Auto Reset. On some faults, when Auto Reset is enabled, the MPS3000 trips and after a 2 Sec. delay resets itself automatically. The fault message on the LCD disappears after 2 Sec. Example: On "U/C Level 1", when Auto Reset function is Enabled, the contactor opens and causes automatic Reset. The motor stops and the "U/C Level 1" message is displayed for only 2 Sec.

Area	Function	Setting	Observation
Reset	Panel Reset	Set Panel Rst: ENABLE. (when not required set to DISABLE)	Activated by the **RESET** key on the MPS3000 front panel. When Panel resetting is not permitted set Panel RST: DSABL. For critical faults, such as "Overload" and "Ground Fault", it is a good practice to prevent Panel Resetting. An authorized person (key holder - few key options are available, according to Discrete input A..D settings**)**) can always reset any fault. **Note**: If **Authorized Key** is locked, front panel Resetting is effective if: a. Panel Reset parameter is "Enabled." For the specific fault displayed. For MPS3000-C, two additional conditions must be fulfilled: b. There is no Start signal (to prevent start as a result of resetting). c. Local/Remote input is in "Local" mode, and
Reset	Remote Reset	Set Remote Reset : ENABLE	The MPS3000 incorporates programmable four Discrete (digital) inputs. Each one can be set for Remote Reset. The MPC3000-C incorporates an additional PLC Reset input. The following conditions will enable PLC Reset. a. Local/Remote input is switched to Remote, and b. PLC/Serial Port input is switched to PLC c. There is no Start signal. Use only momentary reset inputs. !
Reset	Reset via serial link.		For MPS3000, the reset via serial link is always accepted. For MPS3000-C: The following conditions will enable reset via the serial link. a. Local/Remote input is switched to Remote, and b. PLC/Serial Port input is switched to Serial Port.
Output Relays	**Enable Relay-A activation upon trip or Alarm**	Set to ENABLE or DISABLE	Output Relay-A is activated when trip or alarm occurs. Physical activation of the relay occurs if a fault/trip occurs for any of the trip/alarm conditions for which it is set. The relay can also be used (when configured as (I>0) After Trip), to trip an upstream breaker, if the contactor is welded, so current is still > 10% of rated, after trip.
Output Relays	**Enable Relay-B activation upon trip or Alarm**	Set to ENABLE or DISABLE	Output Relay –B is activated when trip or alarm occurs. Physical activation of the relay occurs if a fault/trip occurs for any of the trip/alarm conditions for which it is set.

9.9.2. Multiple Alarm/Trip Considerations

The MPS3000 is designed to accept and store the first alarm it detects. If this alarm has not been reset and an additional alarm occurs, the MPS3000 will not display the second alarm on the LCD nor assign it to the Fault Data page.
Example: If UNBALANCE ALARM occurs and then a THERMAL PRE-ALARM occurs, the MPS3000 will continue displaying UNBALANCE ALARM message on both, LCD and Fault Data page. This is to assist the user in establishing the cause of the alarm.
In case a trip occurs after an alarm, the trip message will override the alarm message.
The table on section 9.9.4 page 48 summarizes the seven factory default settings for each of the faults, and describes when each fault active.

Notes: Prior to modifying this table, make a copy of this table and do not mark on the original. Mark your settings in the empty space available for each value.

For operation in PROTECTION ONLY mode, disable all PLC Reset faults.

9.9.3. Tripping/Alarm Individual Settings

9.9.3.1. MAX START TIME

Fault occurs when starting time is longer then MAX START TIME setting. The MPS3000 assumes end of starting process, when motor current decreases below 110% of the OVERLOAD PICKUP value.
For a default value of 105%, end of starting process is detected at 115% of MOTOR FLC (Motor Full Load Current).

Note: The following description presents the previous mentioned five setting options (Trip, Alarm, Auto Reset, Panel Reset, PLC Reset) available for MAX START TIME. In order to keep the text brief we avoided repeating this description for each of the remaining 51 protection functions.

MAX. START TIME Trip: DISABLE	When Enabled, if starting time exceeds MAX START TIME setting, the MPS3000 trips. If Output A and Output B relays are configured as contactors A & B (common setting for MPS3000-C), then internal relays A and B will open, opening motor contactors. If CONFIG. OUTPUT D parameter is set to TRIP, output D relay energizes. If CONFIG. OUTPUT D parameter is set to TRIP - FAIL SAFE, output D relay de-energizes. Trip condition is latched. Range: DISABLE, ENABLE
MAX. START TIME Alarm: ENABLE	When Enabled, and in case starting time exceeds MAX START TIME setting, If CONFIG. OUTPUT C parameter was set to ALARM FAIL SAFE, output C relay de-energizes. If set to ALARM, output C relay energizes. Alarm condition is latched. Range: DISABLE, ENABLE
MAX START TIME AUTO RST: DSABL.	When Enabled, Automatically resets MAX START TIME fault after motor stops. Range: DISABLE, ENABLE.
MAX. START TIME PANEL RST.:ENABL	When Enabled, allows Front panel resetting Range: DISABLE, ENABLE.
MAX. START TIME REMOT RST:ENABL	When Enabled, allows PLC (Remote) resetting. Range: DISABLE, ENABLE.
MAX. START TIME OUTPUT A.:DISABL	When Enabled, causes output A relay to energize upon MAX START TIME fault. Range: DISABLE, ENABLE.
MAX. START TIME OUTPUT B: DISABL	When Enabled, causes output B relay to energize upon Max Start Time fault. Range: DISABLE, ENABLE.

9.9.3.2. TOO MANY STARTS

Fault occurs when the number of starts exceeds the NUMBER OF STARTS setting during STARTS PERIOD time. Auto Reset, when Enabled, occurs after START INHIBIT time elapsed.
If one of the Discrete inputs A, B, C or D is configured as an Emergency Restart input and if this input (the Emergency Switch) is closed, then all starts performed are ignored. So, TOO MANY STARTS fault is automatically disabled.
Note: Each output relay (A and B), can be configured as # OF STRTS PRE ALRM (Number Of Starts Pre Alarm). In this mode the relay is energized if motor is stopped, as long as a new start would cause TOO MANY STARTS fault. It can be used to prevent the next start as long as it is not allowed, simply by connecting the output relay (A or B) in series with the mains contactor.

9.9.3.3. UNDER CURRENT LEVEL 1

For a running motor, fault occurs when current decreases below U/C LEVEL 1 setting, for a time longer than U/C LEVEL 1 DELAY setting.
Auto reset, when Enabled, occurs when current is above U/C LEVEL 1, or when motor stops or trips.

9.9.3.4. UNDER CURRENT LEVEL 2

For a running motor, fault occurs, when current decreases below U/C LEVEL 2 setting for a time longer than U/C LEVEL 2 DELAY setting.
Auto reset, when Enabled, occurs when the current increases above U/C LEVEL 2, or when the motor stops or trips.

9.9.3.5. LOAD INCREASE

Active only after start process ended (after current decreased to below 110% of OVERLOAD PICKUP

value). Fault occurs when motor average current is above LOAD INCREASE setting for more than 5 seconds. Auto reset, when Enabled, occurs when current decreases to below the LOAD INCREASE setting, or when motor stops or trips.

9.9.3.6. OVER CURRENT LEVEL 1- JAM

This identifies a jam condition for a "running" motor. Fault occurs if after start process has ended, motor average current increases above O/C LEVEL-JAM 1 setting value for more than O/C LVL 1 DELAY. Auto reset, when Enabled, occurs when current decreases below O/C LEVEL 1-JAM, or when motor stops or trips.

9.9.3.7. OVER CURRENT LEVEL 2 - SHORT

This identifies short circuit condition. Fault occurs when any of the motor's line currents exceeds O/C LEVEL 2- SHORT value, for more than O/C LVL 2 DELAY time.
Auto reset, when Enabled, occurs when current decreases to below the O/C LEVEL 2- SHORT value, or when trips motor.

Notes:

1. True RMS line currents are measured, disregarding the average "DC" value. It is designed to prevent nuisance tripping at the very beginning of the starting process (during which DC decaying current is superimposed on the AC Current).
2. Minimum setting of O/C LEVEL 2 DELAY is 0. At 0 setting, the actual time delay is less than 70 ms.
3. O/C LEVEL 2- SHORT is prevented when the highest of any of the line currents exceeds CURRENT INHIBIT setting. It is designed to prevent opening of motor contactor under high short circuit conditions to protect its contacts from being damaged. Fault display: O/C LEVEL 2- SHORT.
4. THERMAL LEVEL 2 (Overload) overrides CURRENT INHIBIT setting.

9.9.3.8. THERMAL LEVEL 1 and 2

The MPS3000 simulates the thermal condition of the motor and stores it in a thermal register. The content of the thermal register is called THERMAL CAPACITY. It simulates the motor temperature. Thermal capacity of 100% is equivalent to a motor running at the absolute maximum allowed temperature. At this point the motor must be tripped.
The following parameters are used to calculate the Thermal Capacity.

CURVE MULTIPLIER

This is a multiplier of the basic standard curve. It enables to shift the entire overload curve. For example, when Curve Multiplier is set to 1, time to trip of a cold motor at 2*In is 29.1 Sec. If Curve Multiplier is set to 10, time to trip of a cold motor at 2*In is 291 Sec.

OVERLOAD PICKUP

THERMAL LEVEL 2 is not active for currents below the OVERLOAD PICKU" value. For a standard motor, leave OVERLOAD PICKUP at its default value of 105%. When current increases above this value a fault will occur after a given time. This time depends on the present value of the THERMAL CAPACITY, on the current level and on CURVE MULTIPLIER parameter.

HOT/COLD RATIO

This parameter, determines the ratio of the available THERMAL CAPACITY for a Hot Motor and for a Cold Motor.
The THERMAL CAPACITY of a Hot motor, is (100 - Hot/Cold Ratio).
Cold Condition **-** When the motor is stopped for a long time, its THERMAL CAPACITY is zero. Therefore, for a cold motor, all the 100% of THERMAL CAPACITY are available for heating (before a trip occurs).
Hot Condition **-** When a motor is running, its temperature increases, and after it has been running for a long time at a current, slightly below the OVERLOAD PICKUP value, a "Hot Condition" has been created. Now, less than 100% of the THERMAL CAPACITY is available.
Example**:** If Hot/Cold Ratio is set to 60%, then for a "Hot" motor, 40% of the THERMAL CAPACITY was used, leaving 60% for additional heating.
For a motor, running for a prolonged time, at lower than OVERLOAD PICKUP current value, the THERMAL CAPACITY is related to the value of the current.
For Example, if motor current is only ½ of the OVERLOAD PICKUP level, then (K=(½)*40%=20%) only 20% of the THERMAL CAPACITY has been used, leaving 80% for additional heating.

RUN COOL T CONST

This is the Cooling Time Constant for a running motor. When motor current is below the OVERLOAD PICKUP value, THERMAL CAPACITY is exponentially reduced, simulating motor cooling. Two different cooling time constants must be used. Cooling time constant is significantly higher for a stopped motor.

STP COOL T CONST

This is the Cooling Time Constant for a stopped motor. When motor is stopped, THERMAL CAPACITY is exponentially reduced, simulating motor cooling. Normally, Cool Time Stop is 3 – 6 times higher than

the RUN COOL T CONST.

UNBALANCE K FCTR (Unbalance Bias Factor)

Unbalanced currents cause additional motor (mainly Rotor) heating. Unbalanced currents cause negative rotating field, which generates rotor voltages and currents at twice the rated frequency. Further heating is caused as a result of the Skin Effect, which causes significant increase of rotor resistance. The Skin Effect is caused by the high frequency induced by the negative sequence field (compared to a frequency of approximately 1Hz, caused by the positive sequence field).

This additional heating is entered into the thermal model using the UNBLANCE K FCTR This factor changes the value of the motor equivalent current (LEQ) used as the input current for the thermal model.

LEQ is given by:

$$LEQ = I\% * \sqrt{(1 + K * (I_2/ I_1)^2)}$$

Where: **I%** - Motor RMS (average of the three phases) current

I_2 - Negative sequence Current

I_1 - Positive Sequence current

K - The above Unbalance Bias Factor

LEQ – Equivalent current, which takes into consideration the negative sequence extra heating.

RTD BIAS

The Thermal model, as explained up to this point is based on current measurements only. It assumes normal ambient working temperature of approximately 40°C. If the ambient temperature is higher, or if forced and natural cooling of the motor is malfunctioning, the winding temperature can be significantly increased.

The RTD BIAS is a possible way to take the actual winding temperature into consideration. The RTD are relatively slow elements, however they sense accurately the real temperature of the windings. Therefore, the RTD measurement can be used to correct the thermal model for slow motor heating, according to the actual winding temperature. The first parameter RTD BIAS allows to disable RTD BIAS, to use RTD1..3 or to use RTD1..6 for the temperature bias.

Note that when enabled, the RTD BIAS can only increase the THERMAL CAPACITY value. It can never decrease it.

RTD BIAS MIN, RTD BIAS MID, RTD BIAS MAX

RTD BIAS is entered to the thermal model by means of the three following parameters: RTD BIAS MIN, RTD BIAS MID, RTD BIAS MAX. The RTD BIAS curve is created by two straight lines drawn between the following three points.

First point (RTD MIN,0): RTD MIN is the (horizontal) Minimum Bias temperature. Below this temperature the RTD Bias has no effect on the thermal model.

Second point (RTD BIAS MID,100-HOT/COLD RATIO): RTD BIAS MID is the normal expected working temperature with 100% load. At this point, the thermal capacity should be 100 – HOT/COLD RATIO.

Third point (RTD BIAS MAX,100): RTD BIAS MAX is the maximum allowed working temperature. At this point, the thermal capacity should be 100%.

When the overload thermal capacity (including Unbalance Bias), is lower than the THERMAL CAPACITY dictated by the RTD BIAS, it will be automatically increased to the value of the RTD BIAS curve value.

Note: If RTD temp is equal or above RTD BIAS MAX the THERMAL CAPACITY will be increased to slightly below 100%. This is to prevent Overload Trip, if the value of the equivalent current is below OVERLOAD PICKUP value. Normally, RTD trip should occur at or before this point.

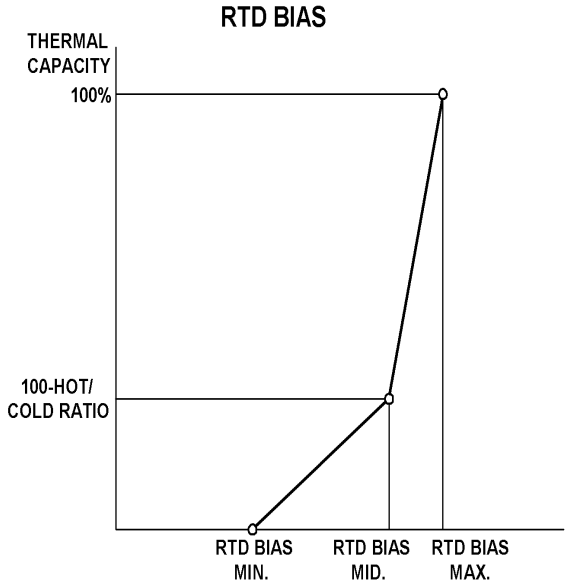


Figure 1 – RTD BIAS

THERMAL LEVEL 1

This setting parameter is intended to be used for alarm only. When THERMAL CAPACITY exceeds the set value, and if enabled, the MPS3000 sets an alarm signal. A host computer can use this signal to read TIME TO TRIP and determine the time left until the MPS3000 will trip.

STALL TIME FACTOR

It is possible to connect a Speed Switch to improve the thermal protection of a motor. When the speed switch detects that the motor is not turning, CURVE MULTIPLIER value is automatically decreased, according to STALL TIME FACT setting.

STALL TIME FACT is the ratio between motor heating thermal time constant when Speed Switch is closed (indicating slow speed) to the time constant in normal starting process. The Speed Switch setting is one of the possible settings for any one of the discrete inputs A, B, C or D.

For the MPS3000-C there is also an additional special input for the speed switch.

Range: 20 - 100 %. Increments of: 1%

The last value of the Thermal Capacity is stored in the non Volatile memory during auxiliary supply failure or disconnection. On restoration of supply, the former value will be re-established.

Note: THERMAL LEVEL 2 overrides CURRENT INHIBIT settings.

Next Figure and Table specify overload trip time delay for Curve Multiplier = 6.

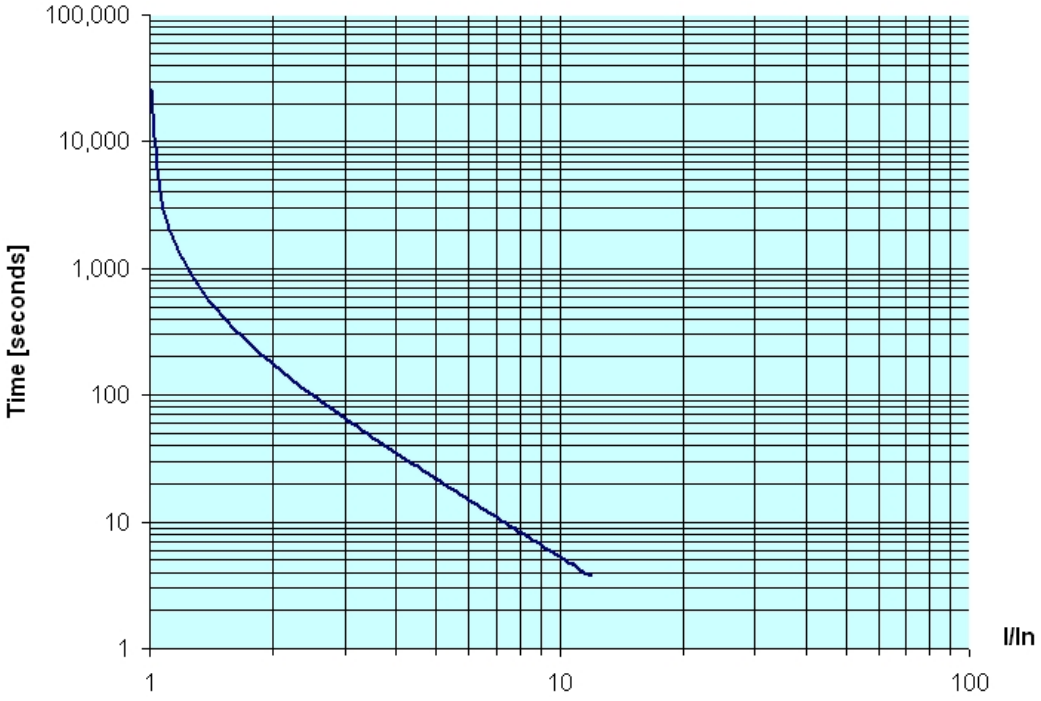


Figure 2 – Time vs. I/In at CURVE MULTIPLIER=6

Thermal Overload Table:

I / In	TIME	I / In	TIME	I / In	TIME	I / In	TIME	I / In	TIME
-	[SEC]	-	[SEC]	-	[SEC]	-	[SEC]	-	[SEC]
1.01	26122	3.20	56.8	5.50	17.9	7.80	8.8	10.10	5.2
1.05	5122	3.30	53.1	5.60	17.3	7.90	8.5	10.20	5.1
1.10	2500	3.40	49.7	5.70	16.7	8.00	8.3	10.30	5.0
1.20	1193	3.50	46.6	5.80	16.1	8.10	8.1	10.40	4.9
1.30	760.8	3.60	43.9	5.90	15.5	8.20	7.9	10.50	4.8
1.40	546.8	3.70	41.3	6.00	15.0	8.30	7.7	10.60	4.7
1.50	419.9	3.80	39.0	6.10	14.5	8.40	7.5	10.70	4.6
1.60	336.5	3.90	36.9	6.20	14.0	8.50	7.4	10.80	4.5
1.70	277.7	4.00	35.0	6.30	13.6	8.60	7.2	10.90	4.5
1.80	234.3	4.10	33.2	6.40	13.1	8.70	7.0	11.00	4.4
1.90	201.1	4.20	31.5	6.50	12.7	8.80	6.9	11.10	4.3
2.00	174.9	4.30	30.0	6.60	12.3	8.90	6.7	11.20	4.2
2.10	153.9	4.40	28.6	6.70	12.0	9.00	6.6	11.30	4.1
2.20	136.7	4.50	27.3	6.80	11.6	9.10	6.4	11.40	4.1
2.30	122.3	4.60	26.0	6.90	11.3	9.20	6.3	11.50	4.0
2.40	110.3	4.70	24.9	7.00	10.9	9.30	6.1	11.60	3.9
2.50	100.0	4.80	23.8	7.10	10.6	9.40	6.0	11.70	3.9
2.60	91.1	4.90	22.8	7.20	10.3	9.50	5.9	11.80	3.8
2.70	83.4	5.00	21.9	7.30	10.0	9.60	5.8	11.90	3.7
2.80	76.7	5.10	21.0	7.40	9.8	9.70	5.6	12.00	3.7
2.90	70.8	5.20	20.1	7.50	9.5	9.80	5.5		
3.00	65.6	5.30	19.4	7.60	9.2	9.90	5.4		
3.10	60.9	5.40	18.6	7.70	9.0	10.00	5.3		

Table values are for Curve Multiplier = 6. For other value of Curve Multiplier divide table values by 6 and multiply by the required Curve Multiplier:

TIME = Time from table * Curve Multiplier / 6.

Example 1: Find time to trip of a cold motor at 5In with CM = 8

From the above table, time to trip at 5In, with CM = 6 is 21.9 Sec.

With CM = 8, time to trip is 8 / 6 * 21.9 = 29.2 Sec.

To find the time for a hot motor find first the time as explained above, then multiply by the HOT/COLD RATIO.

Example 2: *Find time to trip of a hot motor for the above example while HOT/COLD RATIO is set to 60%.*

Solution:

Multiply the result of Example 1 by 0.6 (60%). 29.2 * 0.6 = 15.5 Sec.

THERMAL CAPACITY RESET METHOD

It is not possible to reset (to empty) the THERMAL CAPACITY.

Reset, of THERMAL LEVEL 2, is prevented until THERMAL CAPACITY “cools down" bellow 50%. Therefore, even for a “Key Holder” reset of THERMAL LEVEL 2 trip is not possible for a cooling down period of time.

EMERGENCY RESTART

If one of the Discrete inputs A,B,C or D is configured as an EMERGENCY RESTART input and if this input (Emergency Restart Switch) is closed, then the THERMAL CAPACITY automatically resets to 0 every time the motor is stopped. It is done to allow immediate restarting even if motor is hot. Closing the Emergency Restart switch while motor is already stopped causes also an immediate reset of the thermal capacity. As long as motor is running, the Emergency Restart switch has no effect. Therefore the MPS3000 can still trip for Thermal Level 2 even if the Emergency Restart switch is closed.

Note: If an EMERGENCY RESTART input is used, RTD BIAS should be set to OFF to ensure resetting of the Thermal capacity while motor is stopped.

Warning: Use only for emergency case. Open switch immediately after Emergency is ended.

9.9.3.9. UNBALANCE LEVEL 1

Current unbalance is the Ratio between motor’s Negative Sequence current to its Positive Sequence current.

Unbalance = I_2 / I_1 (Limited to: Unbalance <= 100%)

Where: **I_2 = Negative seq. current, I_1= Positive seq. current**
If Motor average RMS current is less than the rated Motor FLC, then the Unbalance value is decreased by the factor Iavg / FLC, where Iavg is the RMS average of the three phase currents.
Unbalance = (I_2 / I_1) * (Iavg / FLC)
This method prevents nuisance alarming at low currents. The MPS3000 initiates an alarm, UNBALANCE MIN T seconds after the actual unbalance value increases above 50% of UNBALANCE LEVEL 2 setting.
Auto reset, when Enabled, occurs when the actual unbalance decreases to below 50% of UNBALANCE LEVEL 2 setting, or when motor stops or trips.

9.9.3.10. UNBALANCE LEVEL 2

UNBALANCE LEVEL 2 setting, determines the minimum value of actual unbalance for UNBALANCE LEVEL 2 fault.
If the actual unbalance exceeds UNBALANCE LEVEL 2 setting, a time delay is initiated. The time delay is related to U/B LVL 2 MAX T parameter, and to the inverse of the square of the actual unbalance (smaller delay for larger unbalance). Minimum value of the time delay is UNBALANCE MIN T seconds.
Auto reset, when enabled, occurs when the actual unbalance decreases to below UNBAL. LEVEL 2 setting, or when motor stops or trips. See next figure to select the required trip time for any unbalance value.

Note:
Mains phase sequence (positive or negative) is used while calculating positive and negative sequence currents. Mains phase sequence is determined, using to the mains (three phase) voltages.
If the MAINS (all three phases) is not connected to the MPS3000, positive MAINS sequence is assumed. If currents negative sequence is present, UNBALANCE TRIP (if enabled) as well as wrong K factor (Unbalance Bias for Thermal Overload) influence is expected.

9.9.3.11. Setting U/B LEVEL 2 MAX T

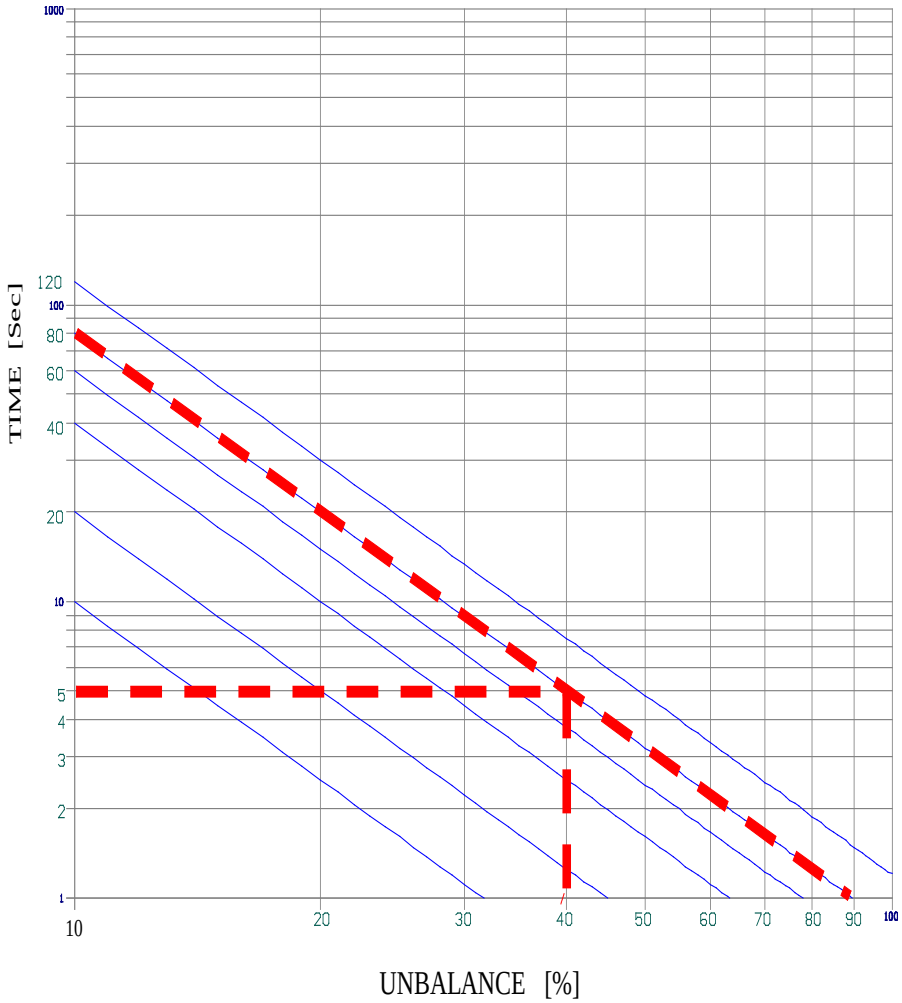


Figure 3 – Unbalance Protection Time Delay

Notes: 1. Select the required trip/alarm time on the vertical axis (at 10% unbalance).
2. Draw horizontal line at the selected point (for example, 5 Sec.).
3. Select an unbalance point (for example 40%).

4. Draw a vertical line at the selected point (the two lines intersect).
5. Draw a parallel line to the diagonal lines at the intersection point.
6. Insert the value of the time at the intersection point (from 5) into parameter U/B LVL 2 MAX T (for example: 80sec).

9.9.3.12. U/V LEVEL (Undervoltage Level)

Active only after the start signal. Fault occurs when the average of the three line to line voltages decreases below U/V LEVEL, for more than U/V DELAY setting. It is possible to connect single phase voltage to the line voltage inputs (terminals 78, 79, 80) and link them together (see section 5.3 - Line Voltages on page 9).
Auto reset, when ENABLED, occurs when average line voltage increases above the U/V Setting value, or when motor trips.
Note: If U/V fault is required even when motor is stopped, option 1 (U/V active in stop condition) should be ordered (consult factory). MPS3000-P detects Start / Run / Stop conditions according to the level of current. If, during normal operation (mains is connected and motor is running), mains is disconnected and under voltage fault is required use option 1 (consult factory).

9.9.3.13. O/V LEVEL 1 (Over Voltage Level 1)

This is active only after the start signal. Fault occurs when the average of three line to line voltages increases above O/V LEVEL 1 setting, for more than 1 second.
Auto reset, when Enabled, occurs when average line voltage decreases below O/V LEVEL 1 value, or when the motor trips.

9.9.3.14. O/V LEVEL 2 (Over Voltage Level 2)

This is active only after the start signal. Fault occurs when the average line to line voltage increases above O/V LEVEL 2 setting, for more than O/V LVL 2 DLY setting.
Auto reset, when Enabled, occurs when average line voltage decreases to below O/V LEVEL 2 value, or when the motor trips.

9.9.3.15. PHASE LOSS

The MPS3000 calculates voltage unbalance according to the difference between maximum and minimum values of the line to line voltages, related to the LINE VOLTS (Vn) setting. Fault occurs when the unbalance level exceeds 20% for more than 2 seconds
Auto reset, when enabled, occurs when the actual Unbalance decreases below 20%.
Note: Set Trip and Alarm to DISABLE, if three phase voltage is not measured.

9.9.3.16. PHASE SEQUENCE

Always Active. Fault occurs when the phase sequence is reversed for more than 2 seconds.
Disable PHASE SEQUENCE both for Trip and for Alarm, if only a single phase is connected to the voltage input terminals.
Auto reset, when Enabled, occurs when a correct phase sequence is detected.
Note: Set Trip and Alarm to DISABLE, if three phase voltage is not measured.

9.9.3.17. GND FAULT LEVEL 1 (Ground Fault Level 1)

Fault occurs when Ground current exceeds GND FAULT LEVEL 1 setting for more than the G/F LEVEL 1 DELAY setting.
Auto reset, when Enabled, occurs when Ground current decreases below GND FAULT LEVEL 1 setting. While starting, G/F DURING START setting parameter overrides G/F LEVEL 1. Designed to eliminate nuisance alarming during start process (with high currents) when residual C/T connection is used.

9.9.3.18. GND FAULT LEVEL 2 (Ground Fault Level 2)

Fault occurs when Ground current exceeds GND FAULT LEVEL 2 setting for more than G/F LEVEL 2 DELAY setting.
Minimum setting of G/F LEVEL 2 DELAY is 0. At 0 setting, the actual time delay is less than 70 ms.
Auto reset, when Enabled, occurs when Ground current decreases below GND FAULT LEVEL 2 setting. While starting, G/F DURING START setting parameter overrides G/F LEVEL 2. Designed to eliminate nuisance tripping during start process (with high currents) when residual C/T connection is used.
Note: GND FAULT LEVEL 2 fault is prevented when the highest of any of the line currents Exceeds CURRENT INHIBIT value. It is designed to prevent opening of motor contactor under high short circuit conditions, to protect its contacts from being damaged.

9.9.3.19. COMM. PORT FAILED (Communication Port Failed)

Fault occurs when the MPS3000 detects three consecutive transmissions from the host computer, in which a parity bit, and/or the CRC word are wrong.
Auto reset, when Enabled, occurs when a transmission from the host computer is received properly.

9.9.3.20. INTERNAL FAILURE

The MPS3000 incorporates a built in Test program. Operating the self test program is done from a special
TEST/MAINTENANCE OPTIONS page. SELF TEST PASSED message, after completion of the built in test, indicates that the MPS3000 functions properly. SELF TEST FAILED, together with an error code (for factory use only) and Internal Fault Led "ON" indicates a fault condition.
Auto reset, when Enabled, occurs when a successful test was performed and its result is SELF TEST PASSED message.
Note: Most of the MPS3000 self test programs are running continuously (much slower then the main program) in the "background".

9.9.3.21. CONTROL CIR. OPEN & WELDED CONTACTOR (Control Circuit Open & Welded Contactor)

The MPS3000-C determines if the motor contactors are open or closed by checking the position of their auxiliary contacts.
Any change in the position of the internal relays A and B (controlling the contactors) is followed by checking their contacts position.
Please note that the CONTROL OPEN / WELDED CONTACTOR protections for contactor A are operative only if CONFIG. INPUT A and B are set to CONTACTOR A N.C. and N.O. respectively. Same is correct for CONTACTOR B and CONFIG. INPUT C and D.
CONTROL CIR. OPEN: Fault occurs, if a change in the contactor's auxiliary contacts is not recognized after energizing the internal relays A or B. Such a situation usually indicates, a CONTROL CIR. OPEN fault.
WELDED CONTACTOR: Fault occurs, if a change in the contactor's auxiliary contacts is not recognized after
de-energizing the internal relays A or B. Such a situation usually indicates a WELDED CONTACTOR fault.
Auto reset, when Enabled, occurs when motor contactors properly follow the MPS3000-C commands.
Note: If motor contactors auxiliary contacts are not connected to the MPS3000-C Inputs, both the alarm and trip of CONTROL CIR. OPEN and WELDED CONTACTOR faults must be disabled.
Note: When CONTROL CIR. OPEN and WELDED CONTACTOR faults are disabled, "Hard-wired Start" and "Hard-Wired Stop" which receive information from the contactors auxiliary contacts are inoperative.

9.9.3.22. EXTERNAL FAULT 1 / 2 / 3

EXTERNAL FAULT 1, 2 or 3 occurs when the MPS3000 detects closed contact between the EXTERNAL FAULT 1, EXTERNAL FAULT 2 or EXTERNAL FAULT 3 input terminals respectively. These inputs can be used for any external faults.
In the MPS3000, each one of the Discrete inputs A...D can be configured for an EXTERNAL FAULT.
The MPS3000-C, has additional three inputs specifically designed for EXTERNAL FAULTS 1...3.
Auto reset of EXTERNAL FAULT X, when Enabled, occurs when the EXTERNAL FAULT X input circuit opens.

9.9.3.23. RTD 1-10, LEVEL 1-2 (Temperature 1.. 10 Level 1.. 2)

High temperature condition is detected according to RTD measured resistance (RTD is a positive temperature coefficient device). For TX LEVEL 1 (or TX LEVEL 2) fault condition is detected when the measured resistance of any channel x exceeds its TX LEVEL 1 (or TX LEVEL 2) setting. Fault occurs after a fixed time delay of 2 seconds. Auto reset, when Enabled, occurs when RTD resistance decreases below RTD x LEVEL 1 (or RTD x LEVEL 2).

Notes:

1. A different model of MPS3000 incorporates six RTD input circuits plus four Thermistor input circuits. When this type of unit is used, PTC (Positive Temperature Coefficient) or NTC (Negative Temperature Coefficient) types of thermistors can be selected. If PTC is selected, Fault occurs when resistance is above the set value. If NTC is selected, fault occurs when resistance is below the set value.
2. If the RTD connector is suddenly disconnected, the MPS reads ????. If Level 1 is set as Alarm and Level 2 is set as Trip the MPS3000 will cause Alarm only and will not Trip.

The table below shows the resistances of the three commonly used types of RTDs.
Please note that Copper RTD requires different model of MPS3000 than the PT100 or Ni120.

Resistance/Temperature Conversion Table

TEMP (°C)	Copper 10 Ohms	Pt.100 Ohms (DIN 43760)	Ni 120 Ohms
0	9.04	100.00	120.00
10	9.42	103.90	127.17
20	9.81	107.79	134.52
30	10.19	111.67	142.06
40	10.58	115.54	149.80
50	10.97	119.40	157.75
60	11.35	123.24	165.90
70	11.74	127.07	174.27
80	12.12	130.89	182.85
90	12.51	134.70	191.64
100	12.90	138.50	200.64
110	13.28	142.29	209.85
120	13.67	146.06	219.29
130	14.06	149.82	228.95
140	14.44	153.58	238.84
150	14.83	157.32	248.95
160	15.22	161.04	259.30
170	15.61	164.76	269.89
180	16.00	168.46	280.77
190	16.39	172.16	291.95
200	16.78	175.84	303.46

9.9.3.24. UNDER PWR LVL 1 (Under Power Level 1)

For a running motor, fault occurs when motor power decreases below UNDER PWR LVL 1 setting for a period of time longer than U/P LVL 1 DELAY setting.
Auto reset, when Enabled, occurs when the power increases above UNDER PWR LVL 1 level or when the motor trips.
Note: Set Trip and Alarm to DISABLE, if three phase voltage is not connected.

9.9.3.25. UNDER PWR LVL 2 (Under Power Level 2)

For a running motor, fault occurs when motor power decreases below UNDER PWR LVL 2 setting for a period of time longer than U/P LVL 2 DELAY setting.
Auto reset, when Enabled, occurs when the power increases above UNDER PWR LVL 2 level or when the motor trips.
Note: Set Trip and Alarm to DISABLE, if three phase voltage is not connected.

9.9.3.26. LOW POWER FACTOR

For a running motor, fault occurs when motor power factor decreases below LOW POWER FACTOR setting for a period of time longer than LOW PF DELAY setting.
Auto reset, when Enabled, occurs when the power factor increases above LOW POWER FACTOR level or when the motor trips.
Note: Set Trip and Alarm to DISABLE, if three phase voltage is not connected.

9.9.3.27. ANALOG INPUTS FAULTS

The MPS3000 incorporates four analog inputs assigned for connecting analog sensors, like Vibration Sensor or Level Sensor. When Sensor output is outside minimum or maximum allowed levels, for more than the set time delay, the MPS3000 generates a fault.

9.9.4. Tripping/Alarm Default Settings

In this table, (+) stands for ENABLED, (-) for DISABLED.

No. Fault	Trip	Alarm	Auto Reset	Panel Rst	Remot Rst	Output A	Output B	Active During	ANSI Code
1. Max Start Time	(-) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Start	48
2. Too Many Starts	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Start	66
3. U/C Level 1	(-) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Run	37
4. U/C Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Run	37
5. Load Increased	(-) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Run	51L
6. O/C Level 1- Jam	(+) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Run	51R
7. O/C Level 2- Short	(+) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	50
8. Thermal Level 1	(-) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49/51
9. Thermal Level 2	(+) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49/51
10. Unbalance Level 1	(-) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	46
11. Unbalance Level 2	(+) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	46
12. Undervoltage	(-) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Run + Start	27
13. O/V Level 1	(-) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Run + Start	59
14. O/V Level 2	(+) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Run + Start	59
15. Phase Loss	(+) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	47
16. Phase Sequence	(+) ( )	(+) ( )	(+) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	47
17. GND Fault Level 1	(-) ( )	(+) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	50G
18. GND Fault Level 2	(+) ( )	(+) ( )	(-) ( )	(-) ( )	(-) ( )	(-) ( )	(-) ( )	Always	50N
19. Comm. Port Failed	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	3
20. Internal Failure	(-) ( )	(+) ( )	(-) ( )	(-) ( )	(-) ( )	(-) ( )	(-) ( )	Always	3
21. Control Cir. open	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Beginning of Start	74
22. Welded Contactor	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Beginning of Stop	74
23. External Fault 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	86 or 94
24. External Fault 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	86 or 94
25. External Fault 3	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	86 or 94
26. RTD 1 Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
27. RTD 1 Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
28. RTD 2 Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
29. RTD 2 Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
30. RTD 3 Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
31. RTD 3 Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
32. RTD 4 Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
33. RTD 4 Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
34. RTD 5 Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
35. RTD 5 Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
36. RTD 6 Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
37. RTD 6 Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
38. RTD 7 Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
39. RTD 7 Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
40. RTD 8 Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
41. RTD 8 Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
42. RTD 9 Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
43. RTD 9 Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
44. RTD 10 Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
45. RTD 10 Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	49R
46. Under Pwr Level 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Run	32L
47. Under Pwr Level 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Run	32L
48. Low Power Factor	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Run	55
49. Analog Input # 1	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	??
50. Analog Input # 2	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	??
51. Analog Input # 3	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	??
52. Analog Input # 4	(-) ( )	(-) ( )	(-) ( )	(+) ( )	(+) ( )	(-) ( )	(-) ( )	Always	??

9.9.4.1. Added Options Available in the MPS3000 Which Correspond to ANSI Codes

Speed Switch Input (No Rotation detector)	14
Lock-Out on thermal Trip	86
RTD Bias for Thermal Overload	??
Unbalance Bias for Thermal Overload	??
Low Speed switch of Two-Speed motor	??
Emergency switch effect on Thermal Overload (reset of thermal capacity when stopped)	??
Emergency switch effect on Too Many Starts (not recording starts while in emergency)	??
Fault Simulation (of Voltages, currents, temperature)	??

10. DATA PAGES - MENUS

These menus are accessed by pushing the Data Page button.

10.1. MEASURED DATA

MEASURED *** DATA ***

Display	Description
Vp1 Vp2 Vp3 **277 277 277 V**	Phase to Neutral voltages. Range: 100 V - 12.7 KV.
VL12 VL23 VL31 **480 480 480 V**	Line to Line Voltages. Range: 100 V - 25 KV.
I1 I2 I3 **137 138 139 A**	Line (motor) currents. Range: 1 A - 24 KA.
GROUND CURRENT **0 Amp.**	Ground current. 1 A - 2000A
FREQUENCY **50.0 HZ**	Mains frequency. 40Hz – 70Hz
POWER **97.5 KW**	Total motor power. Range: 0 - 30MW.
REACTIVE POWER **60.5 KVAR**	Total motor reactive power Range: 0 - 30 MVAR
POWER FACTOR **0.89**	Total (Average of three phases) motor power factor. Range : 0.0 - 1.00
T1 T2 T3 **110 111 109 °C**	RTD 1 - 3 Temperature Range: 0°C - 200°C
T4 T5 T6 **110 111 109 °C**	RTD 4 - 6 Temperature Range: 0°C - 200°C
T7 T8 T9 **70 68 ??? °C**	RTD 7 -9 Temperature Range: 0°C - 200°C **Note**: With Thermistors units are (1/10) KΩ ???: Means RTD not connected
T10 **??? °C**	RTD 10 Temperature Range: 0°C - 200°C **Note**: With Thermistors units are (1/10) KΩ ???: Means RTD not connected
ANALOG INPUT # 1 **0%**	Analog Input 1 in % of full range. Range: 0% - 100%
ANALOG INPUT # 2 **0%**	Analog Input 2 in % of full range. Range: 0% - 100%
ANALOG INPUT # 3 **0%**	Analog Input 3 in % of full range. Range: 0% - 100%
ANALOG INPUT # 4 **0%**	Analog Input 4 in % of full range. Range: 0% - 100%

10.2. CALCULATED DATA

CALCULATED
*** DATA ***

Display	Description
MOTOR LOAD CURR. 90 % OF FLC	Motor current as a percentage of MOTOR FLC. Range: 0 - 1200% of Motor FLC.
EQUIVALENT CURR. 90 % OF FLC	Equivalent Motor current (increased by unbalance according to Unbalance K Factor) as a percentage of MOTOR FLC. Range: 0 - 1200% of Motor FLC.
UNBALANCE CURR. 0%	UNBALANCE CURRENT. The ration between Positive Sequence current to Negative Sequence current. If Motor Load is less than 100% then the above ration is multiplied by the factor (Motor Load / 100) to prevent nuisance tripping
THERMAL CAPACITY 30% OF CAPACITY	THERMAL CAPACITY used. Simulates motor's winding temperature according to the selected Thermal Overload Curve, to Unbalance Bias and to RTD Bias. Trip Level = 100%
TIME TO TRIP-O/L NO TRIP EXPECTED	Expected time to trip at the present current value which is above Overload Pickup. Range: No Trip Expected - 18 Hours.
TIME TO START 0 SEC.	Expected time to start, displayed in one of the following cases: • After THERMAL TRIP. This is the expected time of the THERMAL CAPACITY to decay to 50% of the maximum THERMAL CAPACITY. • After TOO MANY STARTS Trip. In this case, maximum value of TIME TO START equals START INHIBIT Time. Range after THERMAL TRIP: 0 - 166 minutes Range after TOO MANY STARTS: 1 - 60 minutes

TIME TO TRIP The expected time until motor trips. (i.e. the time to reach 100% of Thermal Capacity if the present current value is maintained). This value is calculated and displayed on the LCD. The host computer may read this value through the serial link, and try to take some corrective actions.

TIME TO START The expected time until it is possible to re-start after Thermal Trip (i.e. the time to reach 50% of Thermal Capacity) or after Too Many Starts. This value is calculated and displayed on the LCD.

Reset of the THERMAL CAPACITY

If Emergency Restart switch is closed, then Thermal Capacity is automatically reset when motor is stopped, to allow immediate restart of a hot motor.

10.3. LOGICAL INPUTS CONTACT STATUS

Logical Inputs Contact Status

I

t is possible to check the status of any logical input.
Used to check the wiring for system maintenance and debugging.
Note: If the MPS3000 is in PROTECTION ONLY mode only four of the following parameters are displayed:
Discrete Input A, Discrete Input B, Discrete Input C and Discrete Input D.

Display	Description
MPS3000-C only:	
MOTOR STATUS	Available if: * Motor is stopped. * There is no active trip. * Stop contact is closed. * Interlock and Isolator inputs are not locked out. **Note**: If MPS3000 is in PROTECTION ONLY mode, then Stop, Interlock and Isolator inputs have no effect. Range: AVAILABLE, RUNNING, NOT AVAILABLE
DISCRETE INPUT A CONTACT OPEN	Programmable digital input. Range: CONTACT OPEN, CONTACT CLOSED
DISCRETE INPUT B CONTACT OPEN	Programmable digital input. Range: CONTACT OPEN, CONTACT CLOSED
DISCRETE INPUT C CONTACT OPEN	Programmable digital input. Range: CONTACT OPEN, CONTACT CLOSED
DISCRETE INPUT D CONTACT OPEN	Programmable digital input. Range: CONTACT OPEN, CONTACT CLOSED
MPS3000-C ONLY:	
EXTRNL INTERLOCK CLOSE=RUN ENABLE	Interlock input, contact status. Range: CLOSE = RUN ENABLE, OPEN = LOCKED OUT
ISOLATOR N.O. CLOSE=RUN ENABLE	N.O. Auxiliary contact of Isolator. Range: CLOSE = RUN ENABLE, OPEN = LOCKED OUT
ISOLATOR N.C. OPEN=RUN ENABLE	N.C. Auxiliary contact of Isolator. Range: OPEN = RUN ENABLE, CLOSE = ISOLATED
START - A INPUT CONTACT OPEN	Local Start-A input contact status. Range: CONTACT OPEN, CONTACT CLOSED.
START - B INPUT CONTACT OPEN	Local Start-B input contact status. Range: CONTACT OPEN, CONTACT CLOSED.
STOP INPUT CLOSE=RUN ENABLE	Local Stop input contact status Range: CLOSE=RUN ENABLE, OPEN = STOP
LOCAL / REMOTE OPEN = LOCAL	Local / Remote selector switch input contact status. Range: OPEN = LOCAL, CLOSED = REMOTE
PLC CONTROL OPEN = PLC	PLC / Serial port selector switch input contact status. Range : OPEN = PLC, CLOSED = SERIAL PORT
PLC CONTROL - A OPEN = STOP	PLC contactor - A Start / Stop input contact status.

	Range: OPEN = STOP, CLOSED = START/RUN
PLC CONTROL - B OPEN = STOP	PLC contactor - B Start / Stop input contact status. Range: OPEN = STOP, CLOSED = START/RUN
PLC RESET CONTACT OPEN	PLC - reset input contact status. Range: CONTACT OPEN, CONTACT CLOSED.
SPEED SWITCH OPEN= HIGH SPEED	Speed switch input contact status. Range: OPEN = HIGH SPEED, CLOSED = LOW SPEED
AUTHORIZED KEY OPEN = LOCKED	Authorized Key input contact status. Range: OPEN = LOCKED, CLOSE = UNLOCKED
EXTERNAL FAULT 1 OPEN = RUN EN.	External Fault 1 input contact status. Range: OPEN = NO FAULT, CLOSE = FAULT
EXTERNAL FAULT 2 OPEN = RUN EN.	External Fault 2 input contact status. Range: OPEN = NO FAULT, CLOSE = FAULT
EXTERNAL FAULT 3 OPEN = RUN EN.	External Fault 3 input contact status. Range: OPEN = NO FAULT, CLOSE = FAULT

10.4. STATISTICAL DATA

STATISTICAL DATA
- ** -**

TOTAL RUN TIME
10137.5 HOURS

Total run time since commissioning.
Range: 0-30,000 hours.

TOTAL # OF START
1017

Total number of starts since commissioning.
Range: 0-65535

TOTAL # OF TRIPS
12

Total number of trips since commissioning.
Range: 0-65535

LAST STRT PERIOD
5.2 SEC.

Last start time duration.
Range: 0-255 seconds.

LAST START MAX I
350 AMP.

Peak current (highest of three phases) during last start.
Range: 0-24000 amp.

TOTAL ENERGY
457,235 KWH

Total (since last clearing of statistical data) accumulated motor active energy.
Range: 0-10,000,000 KWH.

TOTAL REACT. EN.
265,107 KVARH

Total (since last clearing of statistical data) accumulated motor reactive energy.
Range: 0-10,000,000 KVARH.

MINIMUM VOLTAGE
395 VOLT

Latched (since last reset) minimum value of RMS Line voltage (average of three phases). Measured while motor is starting or running.
Reset is possible when message is displayed, by pressing Reset Key.

MAXIMUM VOLTAGE
395 VOLT

Latched (since last reset) maximum value of RMS Line voltage (average of three phases). Measured while motor is starting or running.
Reset is possible when message is displayed, by pressing Reset Key.

MINIMUM CURRENT
73 AMP.

Latched (since last reset) minimum value of RMS Line Currents (average of three phases), Measure starts 20 seconds after motor is running.
Reset is possible when message is displayed, by pressing Reset Key.

MAXIMUM CURRENT
73 AMP.

Latched (since last reset) maximum value of RMS Line Currents (average of three phases), Measure starts 20 seconds after motor is running.
Reset is possible when message is displayed, by pressing Reset Key.

MIN. FREQUENCY
49.9 HZ

Latched (since last rest) minimum value of mains frequency.
Reset is possible when message is displayed, by pressing Reset Key.

MAX. FREQUENCY
49.9 HZ

Latched (since last rest) maximum value of mains frequency.
Reset is possible when message is displayed, by pressing Reset Key.

10.5. FAULT DATA

FAULT DATA
- ** -**

LAST TRIP
RTD 3 LEVEL 2

Last active fault that was Enabled as a Trip.
Range: all 52 faults.

LAST ALARM
LOAD INCREASED

Last active fault that was Enabled as an Alarm.
Range: all 52 faults.

TRIP I1, I2, I3
129 132 130 A

Values of three line (motor) currents before last trip.
Range: 0-24000 amp.

TRIP GND CURRENT
0 AMP.

Values of Ground Fault current before last trip.
Range: 0-24000 amp.

TRIP Vp1, Vp2,Vp3
277 277 277 V

Values of phase to neutral voltages before last trip.
Range: 0-25000 volt.

LAST 10 TRIPS:

Header of next 10 screens showing the details of last 10 trips with time stamps.

EXTERNAL FAULT 1
08:32 08/05/ 02

Last Trip with its time stamp.

RTD 1 LEVEL 2
13:33 06/13/02

Values of phase to neutral voltages before last trip.
Range: 0-25000 volt.

O/C LEVEL 2 -
SHORT
11:26 03/21/02

Values of phase to neutral voltages before last trip.
Range: 0-25000 volt.

Next 7 Faults (10 in total) are listed here.

11. Test / Maintenance Options

Push Set Page & ▼simultaneously to enter the test & Test & Service page.

TEST/MAINTENANCE
***** OPTIONS *****

The test page is used for running the self-test, displaying program version, storing factory default parameters into the non volatile memory, resetting and storing statistical data, setting of Real Time Clock and for Fault Simulation. All this can only be done by a “key holder". Unauthorized personnel can only view the test screens.

Display	**Description**
RUN SELF TEST ? **PUSH VALUE-UP**	Press ▲ key to initiate the built in test procedure.
BTL-R-16/09/2008 **MPS3K-280908-10**	Program version description.
STORE NOW ? **DEFAULT SETTINGS**	Stores All factory default parameters in the non-volatile memory. Press **Store** and **Set Page** keys simultaneously, to store. DATA SAVED OK message will be displayed for about two seconds.
CLEAR NOW ? **STATISTICAL DATA**	Clears all statistical data. Press **Reset** and **Data Page** keys simultaneously, to reset and store zero values in the non-volatile memory. DATA SAVED OK message will be displayed for about two seconds. The parameters are: • TOTAL RUN TIME • TOTAL # OF STARTS • TOTAL # OF TRIPS • LAST START PERIOD • LAST START MAX I • THERMAL CAPACITY • LAST TRIP • TRIP VOLTAGES AND CURRENTS • ACTIVE ENERGY (KWH) • REACTIVE ENERGY (KVARH) • DATA SAVED OK message will be displayed for about two seconds.
hh.mm **mm.dd.yy** 13:51 09/29/02	Real Time Clock date and time setting. Set and Store any of the five parameters (pointed by cursor) normally, as for any other setting parameter. Note that Store key forwards cursor to next parameter.

Warning

Default storing and resetting of statistical data should be done with care, since it is not possible to retrieve the previous "set page" parameters or statistical data.
Setting Default parameters, delete all previous stored settings. !
Clearing Statistical Data resets all previous statistical data values. !

Note: For longer life, the Real Time Clock uses a backup capacitor and not backup battery. The Backup capacitor retains data and keeps clock running for a few days. If the MPS3000 is not powered for longer period, the clock has to be initialized. Initialization can be done manually as described above or through serial link.

SIMUL. VL1, 2, 3 **400 VOLT**	For Fault Simulation. Set here the required Line to Line voltages (one setting for the three line to line voltages). No need to press the Store key. Can be changed before or while simulation is “running”. Default value is automatically set to LINE

VOLTS (Vn) setting at system page.

SIMUL. I1, 2, 3 120 AMP

For Fault Simulation. Set here the required Currents. It sets the three currents I1, I2, I3 to same value. Next two parameters allow changing of I2 and I3 simulation settings. Can be changed before or while simulation is “running”.

Default value is automatically set to 1.2 times MOTOR FLC setting at system page.

SIMULATION I2 120 AMP

For Fault Simulation. Use to change value of Simulation I2 Current (so, it will be different from Simulation I1). Useful for testing of Unbalance and of Unbalance Bias of Thermal model. Can be changed before or while simulation is “running”.

Default value is automatically set to 1.2 times MOTOR FLC setting at system page.

SIMULATION I3 120 AMP

For Fault Simulation. Use to change value of Simulation I2 Current (so, it will be different from Simulation I1). Useful for testing of Unbalance and of Unbalance Bias of Thermal overload model. Can be changed before or while simulation is “running”.

Default value is automatically set to 1.2 times MOTOR FLC setting at system page.

SIMULATION I0 0 AMP

For Ground Fault Simulation. Use to change value of Simulation I0 Current. Can be changed before or while simulation is “running”. Useful for testing ground fault protection. Default value is automatically set 0.

SIMUL. T1, 2, 3 40 °C

For RTD High Temperature Fault Simulation. Set here the required Simulation Motor Windings Temperature. Useful for testing RTD alarms and Trips as well as RTD Bias for Thermal Overload model. Can be changed before or while simulation is “running”.

Default value is automatically set 40 °C.

RUN SIMULATION? OFF

By setting to Start / Run, the previous voltages, currents and Temperature values are used by the relay as if they were real actual values. Values may be changed before or during “run time”. Useful for Testing the MPS3000 as well as getting familiar with the relay features and operation, “on the Engineer Table”.
Operative only during first ten hours since the MPS3000 is powered. After that time “NOT POSSIBLE NOW” message is displayed.
To Simulate after more than ten hours, turn OFF the Auxiliary power supply, the turn ON again.

Test Example:

When Protection Only setting at system page is set to Yes.

Setting Run Simulation to Start / Run with the default values, causes the currents to equal 120% of rated motor current. Therefore the Start LED is turned ON. If value of current is not changed MAX START TIME may occur after the setting delay. If current is reduced, Run LED is turned ON and the MPS3000 enters to running status.

View the Measured data and the Calculated data. Change Simulation I2 or I3 to cause Unbalance. Change Simulation I0 to check Ground Fault protection. Change Simulation T1,2,3 to check RTD faults protection. Check Thermal Capacity value and influence of RTD and Unbalance Bias.

12. Communication – Serial Link

The MPS3000 is equipped with a powerful data communication system, operating beyond a motor protection controller into the realm of a complete motor management system.

This communication system is unmatched in its reliability, flexibility and ease of use providing the ideal basis for the design of a modern motor management system.

The MPS3000 incorporates RS485 serial link and uses a MODBUS RTU protocol (The protocol is not included in this document) to provides high speed data acquisition to supervisory computers.
Data formats have been carefully structured to provide fast notification of alarms and continuous updates of performance parameters. Load control can be performed from host computers or by PLCs.

The following information and control can be accessed through the communication.

- All Actual data values
- All MPS3000 Parameter Settings (Read & Write)
- All the control commands for the MPS3000-C (such as Start A, Start B, Stop)
- Reset

See MPS3000 Communication instruction manual.

The MPS3000 system is user expandable. No special engineering skills or tools are required.
For small systems, the Host computer can communicate directly with the MPS3000 via a twisted shielded pair.

For larger systems a Data Highway enables multiple MPS3000 connection. Up to 32 MPS3000s can be added on each twisted pair of the Host serial link with full access to all MPS3000's.

The system also performs high speed data acquisition Users therefore have a simple and friendly means of building a fully integrated monitoring and control systems.

System reliability is exceptionally high, meeting the highest standards of reliable communication in the industry. Included in each message is a 16 bit CRC.

Note: Protocols other than MODBUS RTU available upon consultation.
Note: Terminate serial link cable with 120 Ohm resistors at both ends.

13. Technical Specifications

Auxiliary Power Supply

AC /DC Power Supply:

Standard voltage version: 85 - 250 V (for 110V or 220V AC or DC)
Low voltage version: 19 - 60 V (for 24V or 48V AC or DC)
Frequency: DC, 45 to 65 Hz.
Power consumption: Less than 20 VA

Phase Current Inputs (three current)

Method : True RMS, sample time 0.5 ms.
Range: 0.05 to 12 * phase C/T Primary amps setting.
Full scale: 12 * phase C/T Primary amps setting.
Accuracy: ± 1.5% , for 0.9 to 1.5 * C/T Primary amps setting.
± 5% above 1.5 * C/T Primary
± (3% + 0.02 * C/T Primary) below 0.9 * C/T Primary
Power consumption: ≤ 0.1 VA per 1 A at 1 A. input, (Input impedance ≤ 100 mΩ)
≤ 1.0 VA per 5 A at 5 A. input, (Input impedance ≤ 20 mΩ)

Ground Fault Current Inputs (one current)

Method : True RMS, sample time 0.5 ms.
Range: 0.05 to 1.0 * G/F C/T Primary amps setting.
Full scale: 1.0 * G/F C/T Primary amps setting.
Accuracy: ± 3% of full scale.
Power consumption: ≤ 0.1 VA per 1 A at 1 A. input, (Input impedance ≤ 100 mΩ)
≤ 0.5 VA per 5 A at 5 A. input, (Input impedance ≤ 20 mΩ)

Line Voltage Inputs (three voltages, with or without neutral)

Method : True RMS, sample 0.5 ms.
Power consumption: ≤ 0.2 VA

Without VT transformer:

Range: 50 - 750 volts.
Full scale: 750 volts.
Accuracy: ± 1.0% of full scale.

With VT transformer:

Range: 50 - 750 volts * (VT Primary / VT Secondary), limited to 25 KV.
Full scale: 750 volts * (VT Primary / VT Secondary), limited to 25 KV.
Accuracy: ± 1.0% of full scale.

Temperature Inputs (Ten RTDs - three wires or Six RTDs plus Four Thermistors)

Time delay: 2 Sec.
Range: Copper 10, PT100, Ni120: 0°C - 200°C
PTC or NTC thermistor Model: 0 – 25.0 KΩ
Accuracy: ± 3% of resistance.
Max wire resistance: 25% of Sensor resistance at 10°C

Analog Inputs and Outputs:

Range: 0 – 1mA or 0-20mA (different types). 0-20mA type can be set to 0-20mA or 4-20mA.
Accuracy: 2% of Full Scale + 3% of input.

Overload Alarm and Trip Curves (both heating and cooling)

Fault time accuracy: ± 1 second up to 10 seconds.
± 1 second +/- 2% above 10 seconds.

Threshold current level: Overload Pickup ± 1.5%.
RTD Bias, Unbalance Bias.

Total Run Time

Accuracy: ±2%.

Current Unbalance Alarm and Trip

Method: Unbalance = 100 * (Negative Sequence Current / Positive Sequence Current) [%]

If Motor Load < 100% then multiply by * (Motor Load / 100)
This is to prevent nuisance tripping at low current levels.

Level 1

Threshold Unbalance Level 1: 50% of Unbal Current setting ± 2%.
Alarm (fixed) time delay: 1.0 ± 0.5 Sec.

Level 2 Curves

Threshold Unbalance Level 2: Unbal Current setting ± 2%.
Trip time accuracy: ± 1 second up to 10 seconds.
± 1 second +/- 2% above 10 seconds.

Fault Time Delays

Accuracy: ±0.5 Sec. or ±2% of time, which ever is greater, for all but the above mentioned faults and the following exceptions:
* Overcurrent Level 2: When adjusted to 0 >>> 60 ms +/- 20 ms. -0.1/+0.2 Sec. up to 1 Sec.
* Ground fault trip: -0.1/+0.2 Sec. for less than 1 Sec. delay.

Relays Contacts

Rated load: 8A/250 VAC 1800VA.
Maximum voltage: 250VAC.

Dielectric Strength

1500 VAC, for 1 minute, Between Ground (terminal 63) and:

***** Current inputs.
***** Voltage inputs.
***** Auxiliary power supply inputs
***** Control terminals

Power and Reactive Power Measurements

Method: True RMS over three phase voltages and currents.
Range : 0.1 KW - 30MW (0.1 KVAR - 30 MVAR)
Full Scale : 30MW (30 MVAR)
Resolution : 0.1 KW below 1 MW, 0.01 MW above 1 MW.
Accuracy : For V ≥ 90 * VT Primary / VT Secondary & Power factor ≥ 0.5, with three phase voltages.
Two Ranges : 1. For (10% < I ≤ 150%) of C/T primary, accuracy is :
± (2% + 0.01 * C/T Primary/ Motor FLC.) of motor rated Power
2. For (I ≥ 150%) of C/T primary, accuracy is :
± 7% of the display reading

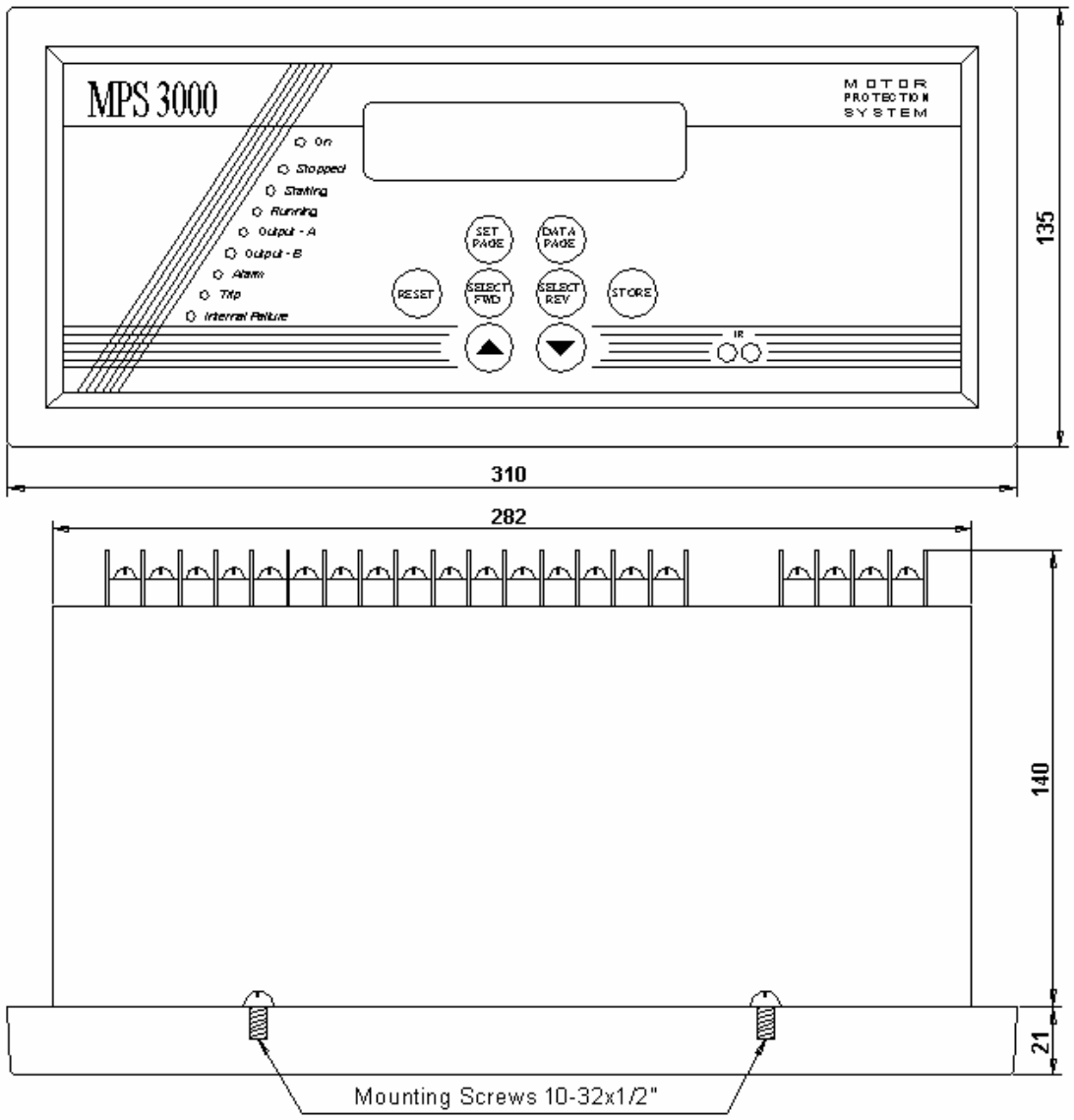
Power Factor

Method: Ratio between total power (P) to total apparent power (VA).
Range : 0.0 - 1.0 leading / lagging.
Resolution : 0.001
Accuracy : For V ≥ 90 * VT Primary / VT Secondary & I ≥ 50% of C/T Primary & Power factor ≥ 0.7 it is ± 0.03

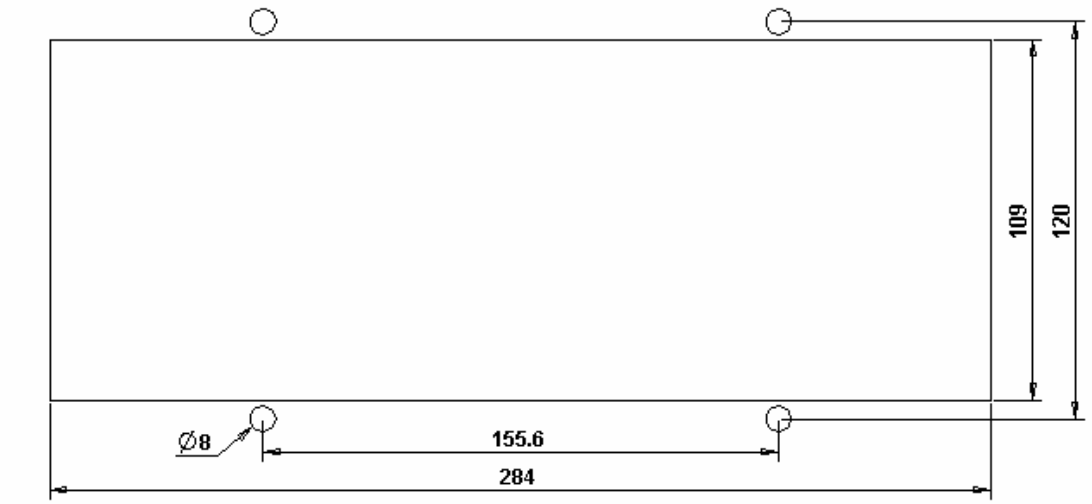
Ambient Temperature 0°C to +50°C

14. Case and Cutout Details

Outside Dimensions



Cutout Details



15. Appendix A - Changes From MPC 2000 to MPS 3000

1. Four programmable discrete (digital) inputs to the MPS3000 (one, before – for Key only).
2. Four programmable Analog outputs
3. Four Programmable Analog Inputs with four new trips (protections)
4. Real time clock.
5. Statistical Data of last 10 trips with time & date stamp.
6. Larger Display.
7. Switch Mode power supply for AC or DC (one unit from 85V to 230V)
8. Baud Rate (MODBUS) up to 19200 bps.
9. MPS3000 includes 10 Temperature sensors. Two models: one (Standard) model with 10 RTD (as before), second (optional) model with 6 RTD and 4 thermistors. Must be ordered from factory. Field modifications are not possible.
10. Control function (for MPS3000-C) with MODBUS function 6 and 16. Functions 1,2,5,15 are canceled.
11. MODBUS new group of 20 user selected actual data parameters for fast scanning.
12. Unbalance calculation using Negative and Positive Sequence instead Imax and Imin.
13. UNBALANCE MIN T (unbalance minimum time = 1..30 sec.) new parameter to prevent too fast response.
14. Standard “American” Thermal Overload curves
15. RTD Bias (of thermal overload)
16. Unbalance Bias (Of Thermal Overload)
17. New program for current, voltage and temperature **fault simulation**. (useful for testing and for learning the MPS3000, "on the engineer table")
18. Power measurement even if single phase voltage is connected (V1n,V2n,V3n = V12)
19. KWH (Energy) Display and KWH output (pulse relay)
20. Programmable Output Relays.
21. Too Many Starts Pre Alarm can be configured to energize output relay.
22. (I > 0) After Trip can be configured to energize output relay B (to trip upstream breaker).
23. Every fault group can be configured to energize output relays A & B (similar to MPR6).
24. NO START PROCESS new setting of STARTING METHOD, to allow switching to run, if I>= 10%.
25. Capture and display of minimum and maximum RMS average (of three phases) voltage and current. Capture of minimum and maximum frequency.
26. G/F During Start setting, new feature to eliminate nuisance ground fault tripping when residual CT connection (not required with Core Balance) is used.
27. New Emergency Restart function. Reset of Thermal capacity by pressing reset twice is canceled.
28. Modified Restart- after mains failure or Auxiliary Power Supply failure.
29. Separate Aux Power Supply and Control Voltage (option –S).
30. KVARH, added.
31. New setting parameter UV ACTIVE AT STOP, to enable/disable Under Voltage protection at stop.

16. Appendix B – Parameters List and Factory Default Settings

Page Name	Name	DEFAULT VALUE	Set Value
SYSTEM	LINE VOLTS (Vn)	480V	
SYSTEM	LINE FREQUENCY	60Hz	
SYSTEM	VT PRIMARY	VT NOT CONNECTED	
SYSTEM	VT SECONDARY	VT NOT CONNECTED	
SYSTEM	MOTOR FLC	100 AMP.	
SYSTEM	CT PRIMARY	100 AMP.	
SYSTEM	GND CT PRIMARY	100 AMP.	
SYSTEM	GND FAULT LVL 1	5% OF FLC	
SYSTEM	G/F LVL 1 DELAY	10 SEC.	
SYSTEM	GND FAULT LVL 2	10% OF FLC	
SYSTEM	G/F LVL 2 DELAY	0.5 SEC.	
SYSTEM	G/F DURING START	100% OF FLC	
SYSTEM	CURRENT INHIBIT	OFF	
SYSTEM	STARTING METHOD	DIRECT ON LINE	
SYSTEM	MAX. TIME IN STAR	10 SEC.	
SYSTEM	TRANSITION TIME	200 mSEC	
SYSTEM	STAR TO DELTA AT	150 % OF FLC	
SYSTEM	CONFIG. OUTPUT A	TRIPPING / ALARM	
SYSTEM	OUTPUT A DELAY	0 SEC.	
SYSTEM	CONFIG. OUTPUT B	TRIPPING / ALARM	
SYSTEM	OUTPUT B DELAY	0 SEC.	
SYSTEM	CONFIG. OUTPUT C	ALARM FAIL SAFE	
SYSTEM	OUTPUT C DELAY	0 SEC.	
SYSTEM	CONFIG. OUTPUT D	TRIP	
SYSTEM	OUTPUT D DELAY	0 SEC.	
SYSTEM	CONFIG INPUT A	AUTHORIZED KEY	
SYSTEM	CONFIG INPUT B	EXT FAULT 1	
SYSTEM	CONFIG INPUT C	EXT FAULT 2	
SYSTEM	CONFIG INPUT D	REMOTE RESET	
SYSTEM	PROTECTION ONLY	YES	
SYSTEM	PARAM. SETTINGS	LOCKED	
VOLTAGE	U/V LEVEL	80% OF Vn	
VOLTAGE	U/V DELAY	5.0 SEC.	
VOLTAGE	U/V ACTIVE AT STOP	DISABLE	
VOLTAGE	U/V STRT PREVENT	OFF	
VOLTAGE	U/V AUTO RESTART	BOTH SUP. & Vin	
VOLTAGE	RESTART DELAY	4.0 SEC.	
VOLTAGE	O/V LEVEL 1	115% OF Vn	
VOLTAGE	O/V LEVEL 2	120% OF Vn	
VOLTAGE	O/V LVL 2 DELAY	1 SEC.	
CURRENT	MAX. START TIME	10 SEC.	
CURRENT	NUMBER OF STARTS	10 SEC.	
CURRENT	STARTS PERIOD	30 MIN.	
CURRENT	START INHIBIT	15 MIN.	
CURRENT	U/C LEVEL 1	50% OF FLC	
CURRENT	U/C LVL 1 DELAY	2 SEC.	
CURRENT	U/C LEVEL 2	40% OF FLC	
CURRENT	U/C LVL 2 DELAY	5 SEC.	
CURRENT	LOAD INCREASE	120% OF FLC	
CURRENT	O/C LEVEL 1- JAM	400% OF FLC	
CURRENT	O/C LVL 1 DELAY	2.0 SEC.	
CURRENT	O/C LVL 2 - SHORT	800% OF FLC	
CURRENT	O/C LVL 2 DELAY	0.5 SEC.	
CURRENT	UNBALANCE LVL 2	15% OF FLC	
CURRENT	U/B LVL 2 MIN T	5 SEC.	

Page Name	Name	DEFAULT VALUE	Set Value
CURRENT	U/B LVL 2 MAX T	30 SEC.	
OVERLOAD	CURVE MULTIPLIER	6	
OVERLOAD	OVERLOAD PICKUP	105% OF FLC	
OVERLOAD	HOT/COLD RATIO	50%	
OVERLOAD	RUN COOL T CONST	10 MIN.	
OVERLOAD	STOP COOL T CONST	30 MIN.	
OVERLOAD	UNBALANCE K FACTOR	5	
OVERLOAD	RTD BIAS	OFF	
OVERLOAD	RTD BIAS MIN	40 °C	
OVERLOAD	RTD BIAS MID	130 °C	
OVERLOAD	RTD BIAS MAX	155 °C	
OVERLOAD	THERMAL LEVEL 1	80% OF CAPACITY	
OVERLOAD	STALL TIME FACTOR	50%	
POWER	RATED PF AT FLC	0.88 LAG	
POWER	UNDER PWR LVL 1	45%	
POWER	U/P LVL 1 DELAY	30 SEC.	
POWER	UNDER PWR LVL 2	25%	
POWER	U/P LVL 2 DELAY	30 SEC.	
POWER	LOW POWER FACTOR	0.8 LAG	
POWER	LOW PF DELAY	30 SEC.	
POWER	KWH PER PULSE	OFF	
TEMPERATURE	RTD TYPE	PLATINUM 100 OHM	
TEMPERATURE	T 7..10 TYPE	RTD	
TEMPERATURE	T 1 LEVEL 1	120 °C	
TEMPERATURE	T 1 LEVEL 2	140 °C	
TEMPERATURE	T 2 LEVEL 1	120 °C	
TEMPERATURE	T 2 LEVEL 2	140 °C	
TEMPERATURE	T 3 LEVEL 1	120 °C	
TEMPERATURE	T 3 LEVEL 2	140 °C	
TEMPERATURE	T 4 LEVEL 1	120 °C	
TEMPERATURE	T 4 LEVEL 2	140 °C	
TEMPERATURE	T 5 LEVEL 1	120 °C	
TEMPERATURE	T 5 LEVEL 2	140 °C	
TEMPERATURE	T 6 LEVEL 1	120 °C	
TEMPERATURE	T 6 LEVEL 2	140 °C	
TEMPERATURE	T7 LEVEL 1	80 °C	
TEMPERATURE	T7 LEVEL 2	100 °C	
TEMPERATURE	T8 LEVEL 1	80 °C	
TEMPERATURE	T8 LEVEL 2	100 °C	
TEMPERATURE	T9 LEVEL 1	80 °C	
TEMPERATURE	T9 LEVEL 2	100 °C	
TEMPERATURE	T10 LEVEL 1	80 °C	
TEMPERATURE	T10 LEVEL 2	100 °C	
ANALOG I/O	ANALOG OUT TYPE	4..20MA	
ANALOG I/O	ANALOG OUT 1 PARAM	AVERAGE CURRENT	
ANALOG I/O	ANALOG OUT 1 MIN	0% OF FLC	
ANALOG I/O	ANALOG OUT 1 MAX	200% OF FLC	
ANALOG I/O	ANALOG OUT 2 PARAM	AVG. LINE VOLTS	
ANALOG I/O	ANALOG OUT 2 MIN	0% OF Vn	
ANALOG I/O	ANALOG OUT 2 MAX	200% OF Vn	
ANALOG I/O	ANALOG OUT 3 PARAM	THERMAL CAPACITY	
ANALOG I/O	ANALOG OUT 3 MIN	0% OF CAPACITY	
ANALOG I/O	ANALOG OUT 3 MAX	200% OF CAPACITY	
ANALOG I/O	ANALOG OUT 4 PARAM	MAX OF T1..T3	
ANALOG I/O	ANALOG OUT 4 MIN	0 °C	
ANALOG I/O	ANALOG OUT 4 MAX	200 °C	

Page Name	Name	DEFAULT VALUE	Set Value
ANALOG I/O	ANALOG IN 1 TYPE	4..20MA	
ANALOG I/O	ANALOG IN 1 LEVEL	ABOVE 50%	
ANALOG I/O	ANALOG IN 1 DELAY	10 SEC.	
ANALOG I/O	ANALOG IN 2 TYPE	4..20MA	
ANALOG I/O	ANALOG IN 2 LEVEL	ABOVE 50%	
ANALOG I/O	ANALOG IN 2 DELAY	10 SEC.	
ANALOG I/O	ANALOG IN 3 TYPE	4..20MA	
ANALOG I/O	ANALOG IN 3 LEVEL	ABOVE 50%	
ANALOG I/O	ANALOG IN 3 DELAY	10 SEC.	
ANALOG I/O	ANALOG IN 4 TYPE	4..20MA	
ANALOG I/O	ANALOG IN 4 LEVEL	ABOVE 50%	
ANALOG I/O	ANALOG IN 4 DELAY	10 SEC.	
TRIP/ALARM	MAX START TIME	TRIP: N, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	TOO MANY STARTS	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	U/C LEVEL 1	TRIP: N, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	U/C LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	LOAD INCREASED	TRIP: N, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	O/C LEVEL 1 - JAM	TRIP: Y, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	O/C LVL 2 - SHORT	TRIP: Y, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	THERMAL LEVEL 1	TRIP: N, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	THERMAL LEVEL 2	TRIP: Y, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	UNBALANCE LVL 1	TRIP: N, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	UNBALANCE LVL 2	TRIP: Y, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	UNDERVOLTAGE	TRIP: N, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	O/V LEVEL 1	TRIP: N, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	O/V LEVEL 2	TRIP: Y, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	PHASE LOSS	TRIP: Y, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	PHASE SEQUENCE	TRIP: Y, ALARM: Y, AUTORESET: Y, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	GND FAULT LVL 1	TRIP: N, ALARM: Y, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	GND FAULT LVL 2	TRIP: Y, ALARM: Y, AUTORESET: N, PANELRESET: N, REMOT RST: N, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	COMM PORT FAILED	TRIP: N, ALARM: N, AUTORESET: Y, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	INTERNAL FAILURE	TRIP: N, ALARM: Y, AUTORESET: N, PANELRESET: N, REMOT RST: N, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	CONTROL CIR. OPEN	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	WELDED CONTACTOR	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	EXTERNAL FAULT 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	EXTERNAL FAULT 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	EXTERNAL FAULT 3	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 1 LEVEL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 1 LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 2 LEVEL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 2 LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 3 LEVEL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 3 LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 4 LEVEL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 4 LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 5 LEVEL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 5 LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 6 LEVEL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 6 LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 7 LEVEL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 7 LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 8 LEVEL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 8 LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 9 LEVEL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 9 LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	RTD 10 LEVEL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	

Page Name	Name	DEFAULT VALUE	Set Value
TRIP/ALARM	RTD 10 LEVEL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	UNDER PWR LVL 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	UNDER PWR LVL 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	LOW POWER FACTOR	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	ANALOG IN 1	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	ANALOG IN 2	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	ANALOG IN 3	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
TRIP/ALARM	ANALOG IN 4	TRIP: N, ALARM: N, AUTORESET: N, PANELRESET: Y, REMOT RST: Y, OUTPUTA: N, OUTPUTB: N	
COMMUNICATION	BAUD RATE	19200	
COMMUNICATION	ADDRESS NUMBER	OFF	
COMMUNICATION	S. LINK PAR. SAVE	DISABLE	
COMMUNICATION	FRONT COM ADDRESS	OFF	
STATISTICAL DATA		TOTOL RUN TIME	
STATISTICAL DATA		TOTAL # OF START	
STATISTICAL DATA		TOTAL # OF TRIPS	
STATISTICAL DATA		LAST STRT PERIOD	
STATISTICAL DATA		LAST STRT MAX I	
STATISTICAL DATA		TOTAL ENERGY	
STATISTICAL DATA		TOTAL REACT. EN.	
STATISTICAL DATA		MINIMUM VOLTAGE	
STATISTICAL DATA		MAXIMUM VOLTAGE	
STATISTICAL DATA		MINIMUM CURRENT	
STATISTICAL DATA		MAXIMUM CURRENT	
STATISTICAL DATA		MIN. FREQUENCY	
STATISTICAL DATA		MAX. FREQUENCY	
FAULT DATA		LAST TRIP	
FAULT DATA		LAST ALARM	
FAULT DATA		TRIP I1, I2, I3	
FAULT DATA		TRIP GND CURRENT	
FAULT DATA		TRIP Vp1, Vp2, Vp3	
FAULT DATA		LAST TRIP -1	
FAULT DATA		LAST TRIP -2	
FAULT DATA		LAST TRIP -3	
FAULT DATA		LAST TRIP -4	
FAULT DATA		LAST TRIP -5	
FAULT DATA		LAST TRIP -6	
FAULT DATA		LAST TRIP -7	
FAULT DATA		LAST TRIP -8	
FAULT DATA		LAST TRIP -9	
FAULT DATA		LAST TRIP -10	

17. Appendix C – Ordering Information

MPS-3000	P-	V-	1P-	2-	0-	M-	S
	Relay Type	Construction	Thermal Sensor	Supply/ Control Voltage	Required Options	Comm.	Front Panel

Relay Type	
Specify	**Description**
P	Motor Protection Relay
C	Motor protection Controller

Construction	
Specify	**Description**
V	Vertical
H	Horizontal

Thermal Sensor	
Specify	**Description**
1P	Ten RTD Platinum 100 ohm/Nickel 120 ohm
1C	Ten RTD Copper 10 ohm
TP	Four Thermistors + six RTD (Pt100)
TC	Four Thermistors + six RTD (Copper)

Supply/Control Voltage	
Specify	**Description**
2	110-230V 50/60Hz or DC (+10% / -15%)
2S	110 - 230 Vac/dc with separate AUX. Power Supply and Control Voltage
3	19 - 60 Vdc

Required Options	
Specify	**Description**
0	No Option
2	Trip on disconnected RTD
Z	Bazan

Communication	
Specify	**Description**
M	RS485 with MODBUS protocol
P	Rear Profibus connection and front RS232 with MODBUS protocol at fixed baud rate of 9600bps (Option “P” available only in vertical construction. For option “P” in horizontal construction – Consult factory)

Front Panel	
Specify	**Description**
S	Standard
N	Consult factory
I	Consult factory
T	Consult factory

Additional request: Provide RS232 null modem cable for front Modbus communication- cat. No. HARN529079.